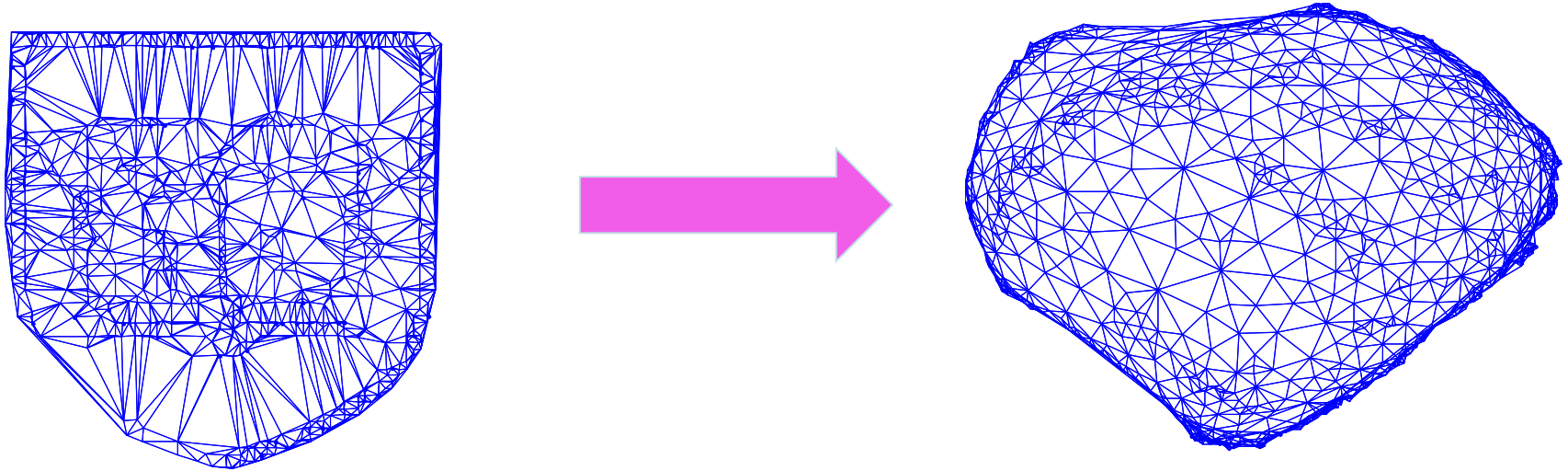


Laplacian Matrices of Graphs: Spectral and Electrical Theory



Daniel A. Spielman
Dept. of Computer Science
Program in Applied Mathematics
Yale University

Toronto, Sep. 28, 2011

Outline

Introduction to graphs

Physical metaphors

Laplacian matrices

Spectral graph theory

A very fast survey

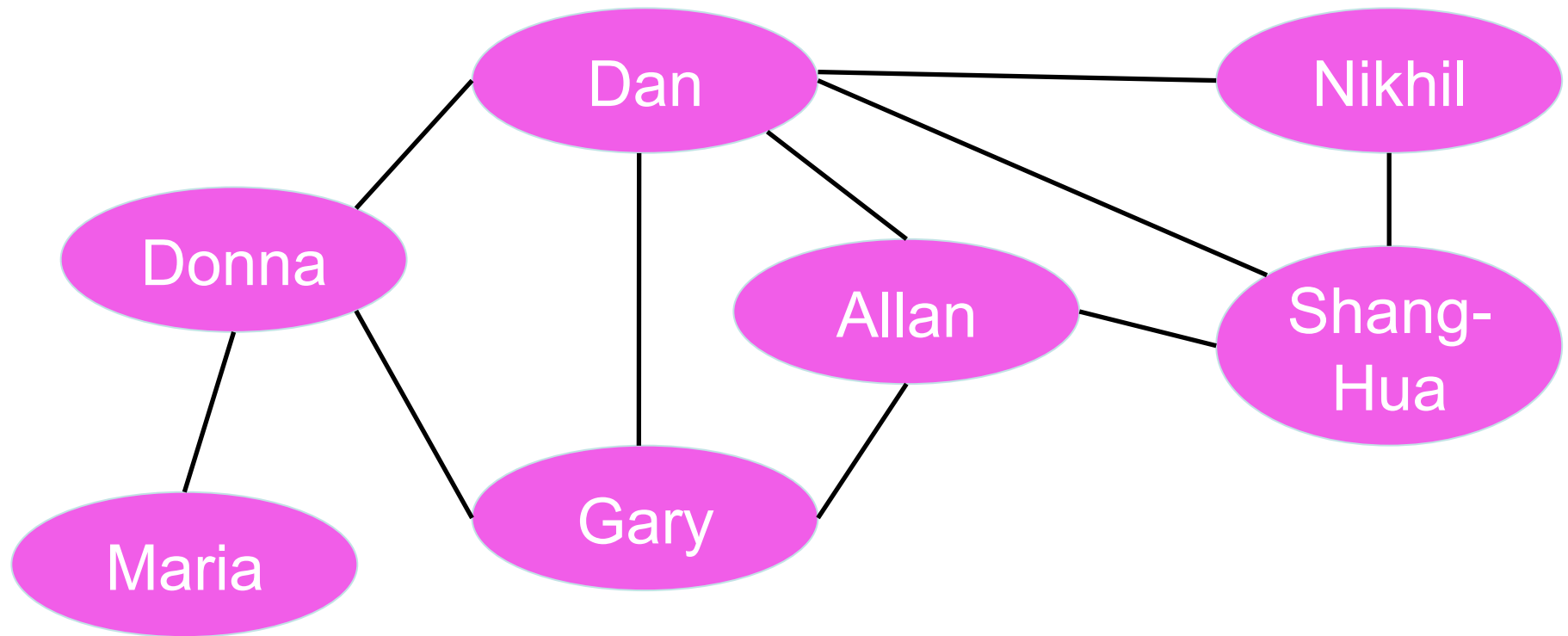
Trailer for lectures 2 and 3

Graphs and Networks

V: a set of vertices (nodes)

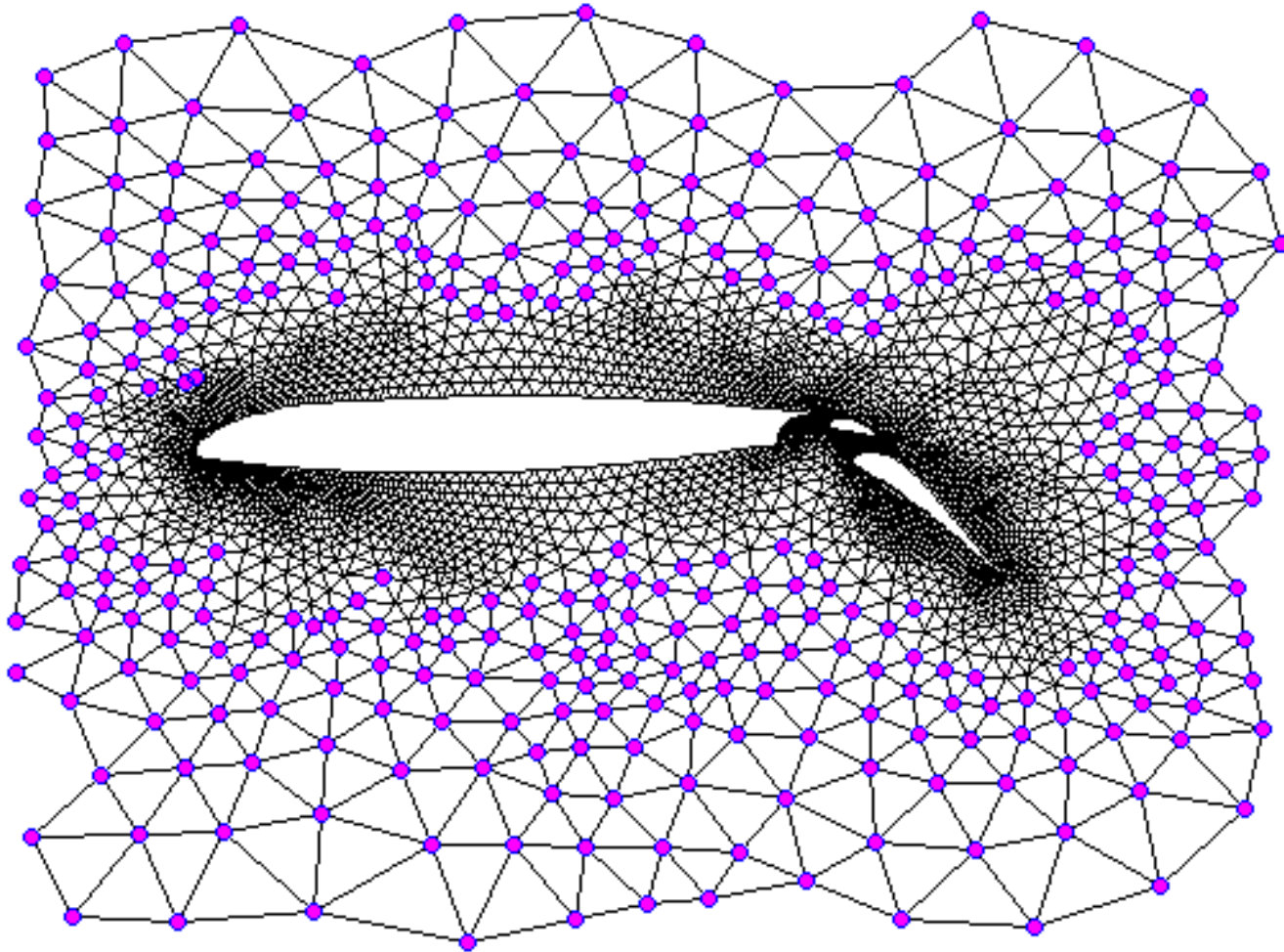
E: a set of edges

an edge is a pair of vertices

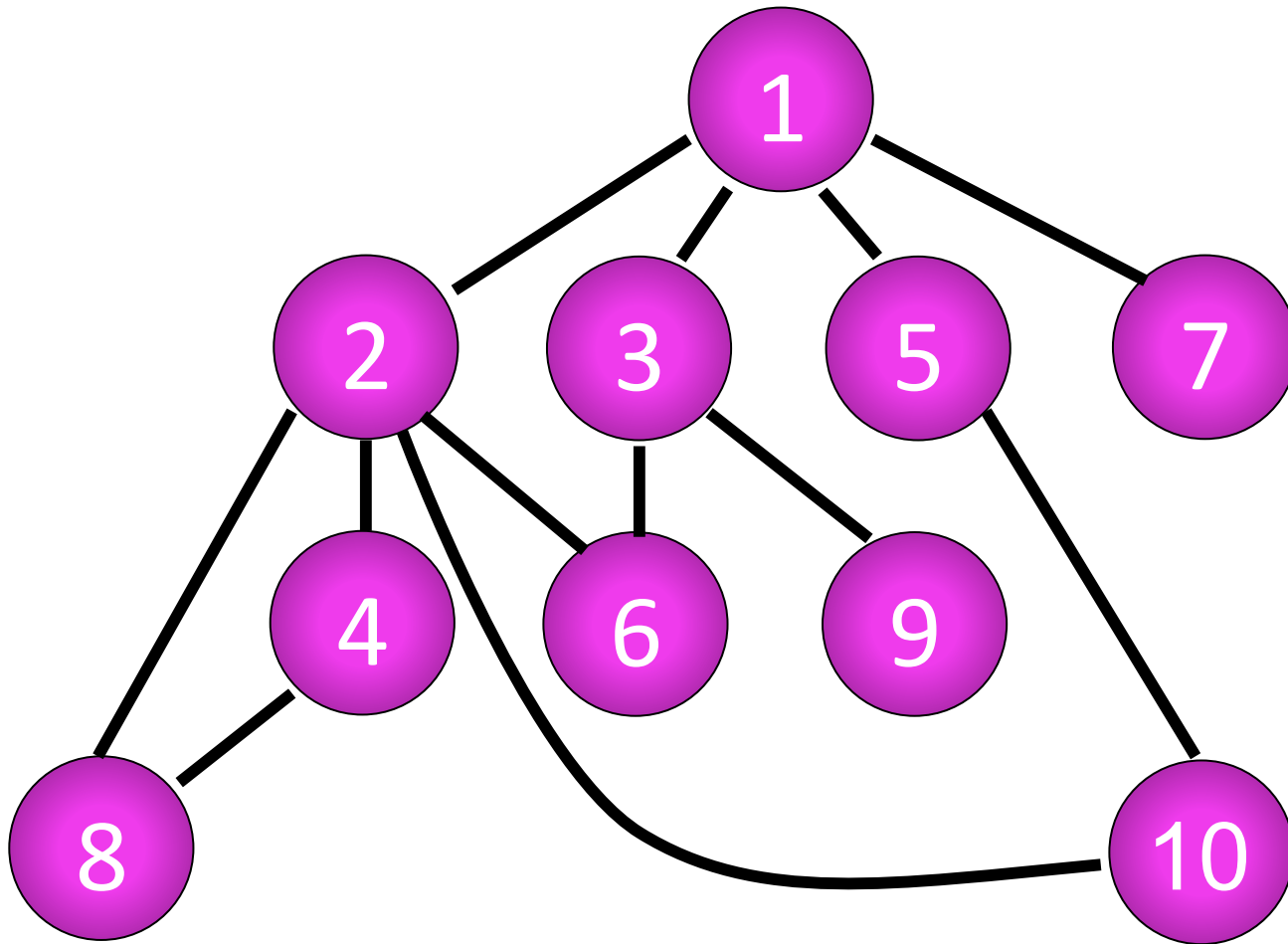


Difficult to draw when big

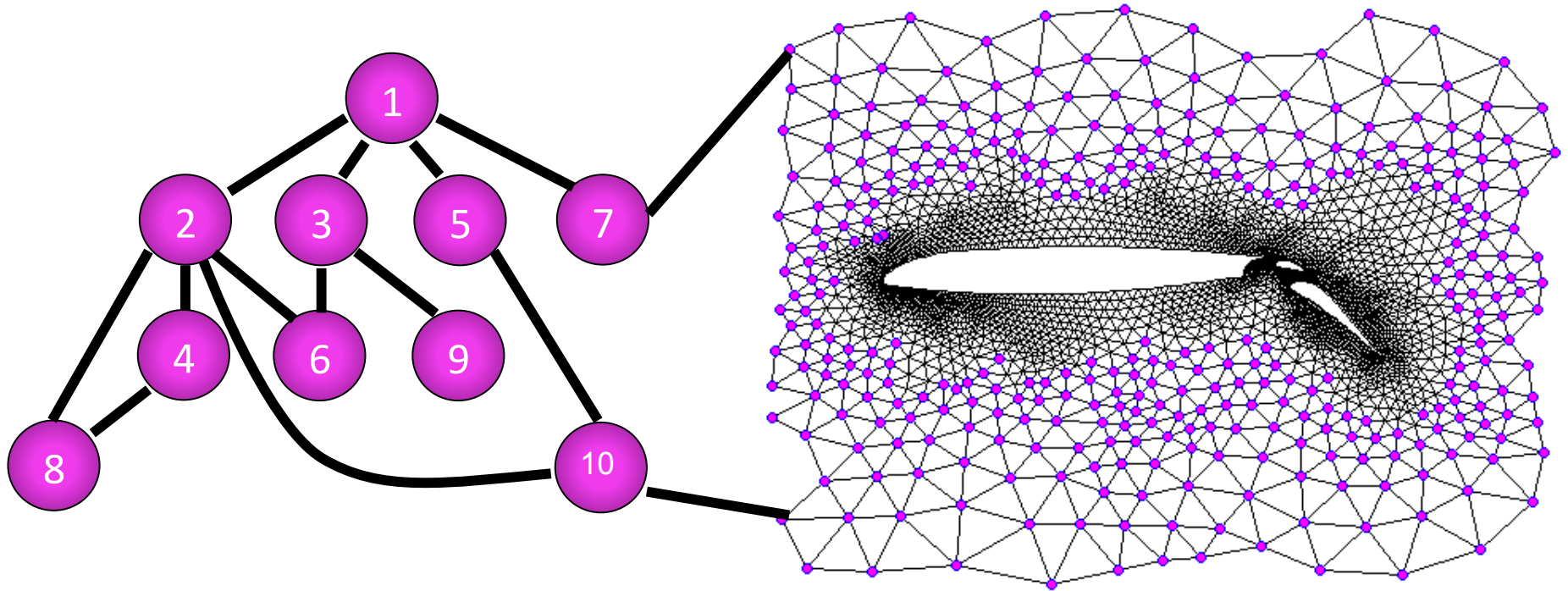
Examples of Graphs



Examples of Graphs



Examples of Graphs



How to understand a graph

Use physical metaphors

Edges as rubber bands

Edges as resistors

Examine processes

Diffusion of gas

Spilling paint

Identify structures

Communities

How to understand a graph

Use physical metaphors

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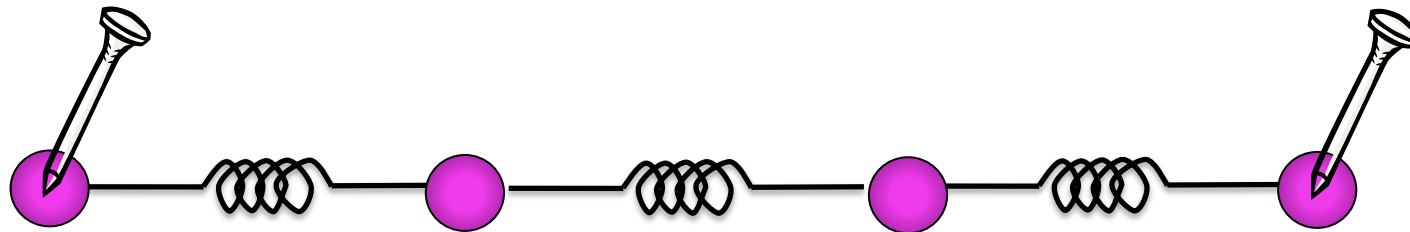
Identify structures

Communities

Graphs as Spring Networks

View edges as rubber bands or ideal linear springs
spring constant 1 (for now)

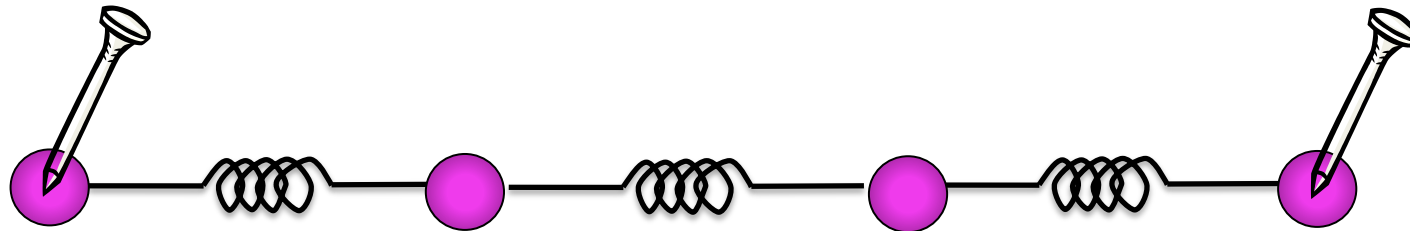
Nail down some vertices, let rest settle



Graphs as Spring Networks

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spring constant 1 (for now)

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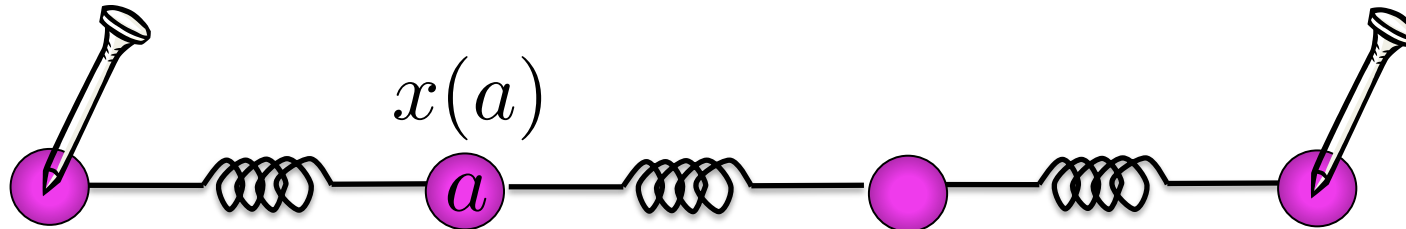


When stretched to length ℓ

potential energy is $\ell^2/2$

Graphs as Spring Networks

Nail down some vertices, let rest settle.



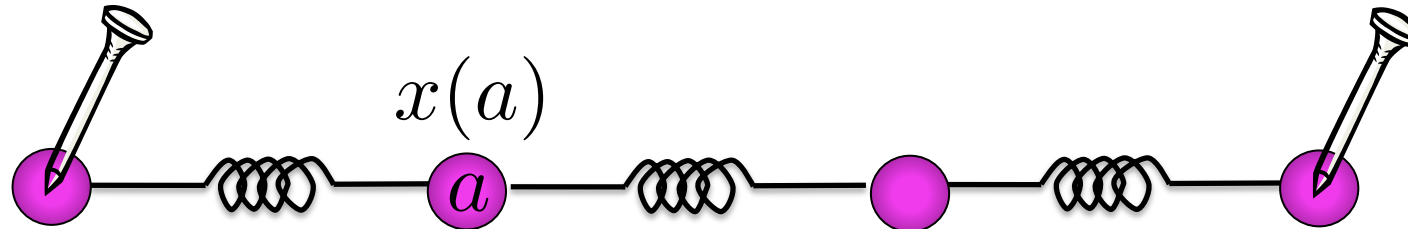
Physics: position minimizes total potential energy

$$\frac{1}{2} \sum_{(a,b) \in E} (x(a) - x(b))^2$$

subject to boundary constraints (nails)

Graphs as Spring Networks

Nail down some vertices, let rest settle



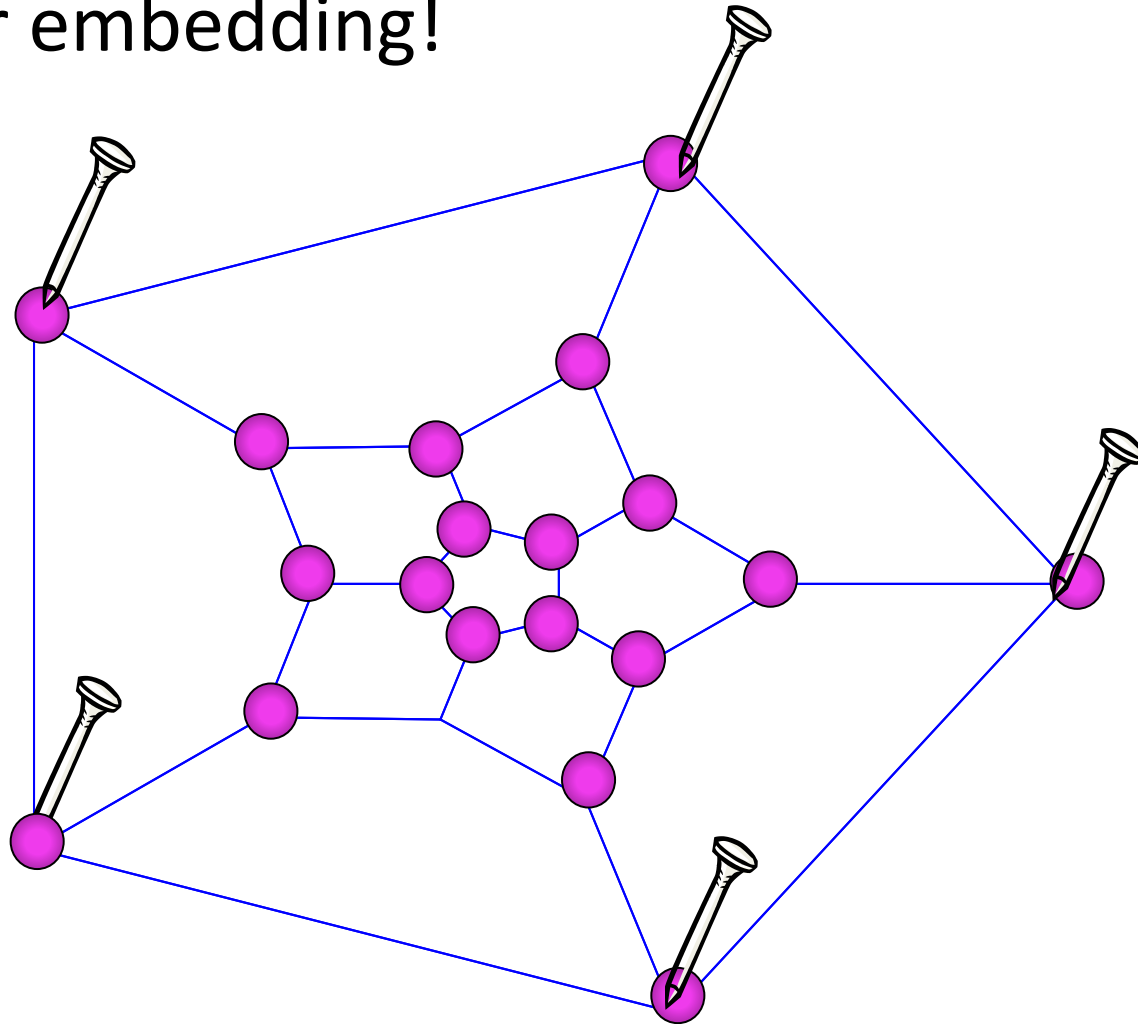
Energy minimized when
free vertices are averages of neighbors

$$\vec{x}(a) = \frac{1}{d_a} \sum_{(a,b) \in E} \vec{x}(b)$$

d_a is *degree* of a , number of attached edges

Tutte's Theorem '63

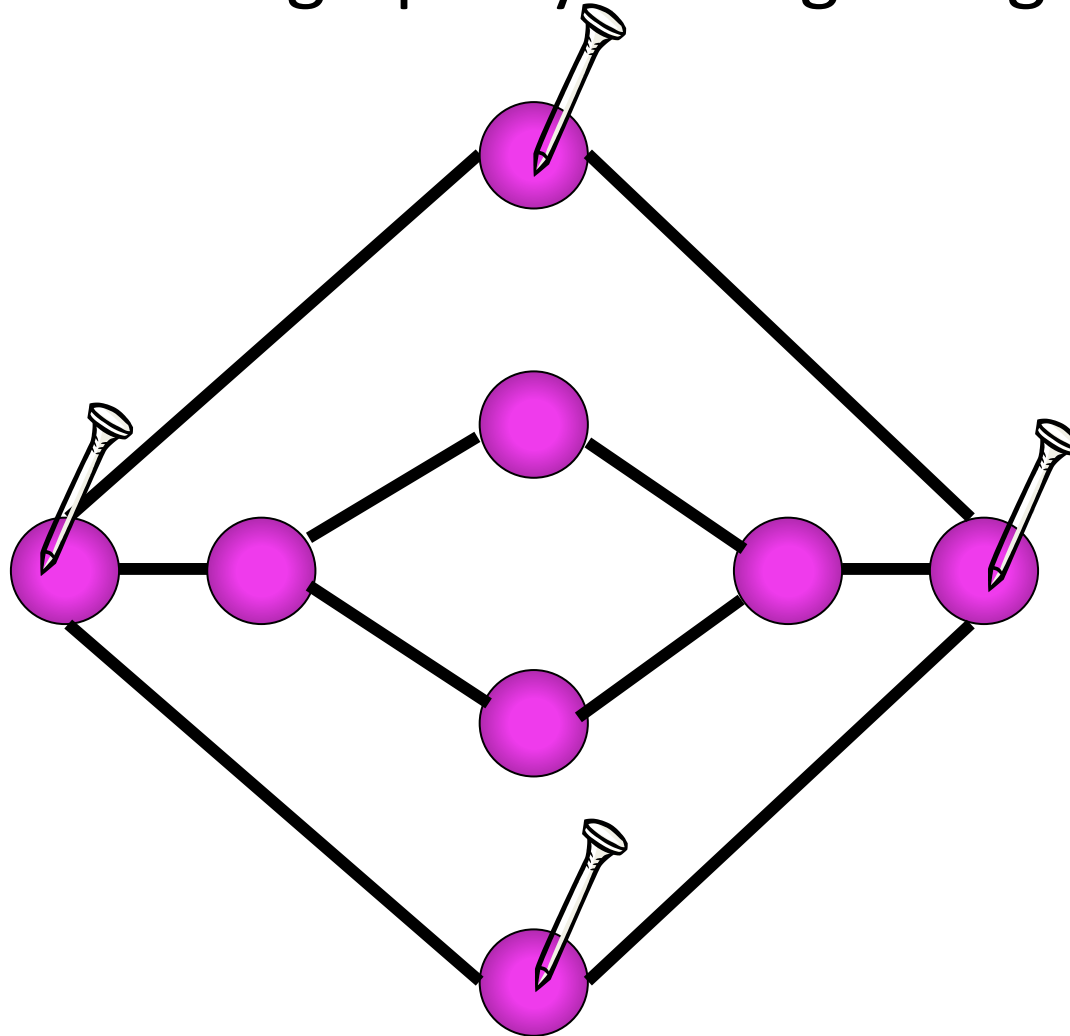
If nail down a face of a planar 3-connected graph,
get a planar embedding!



Tutte's Theorem '63

3-connected:

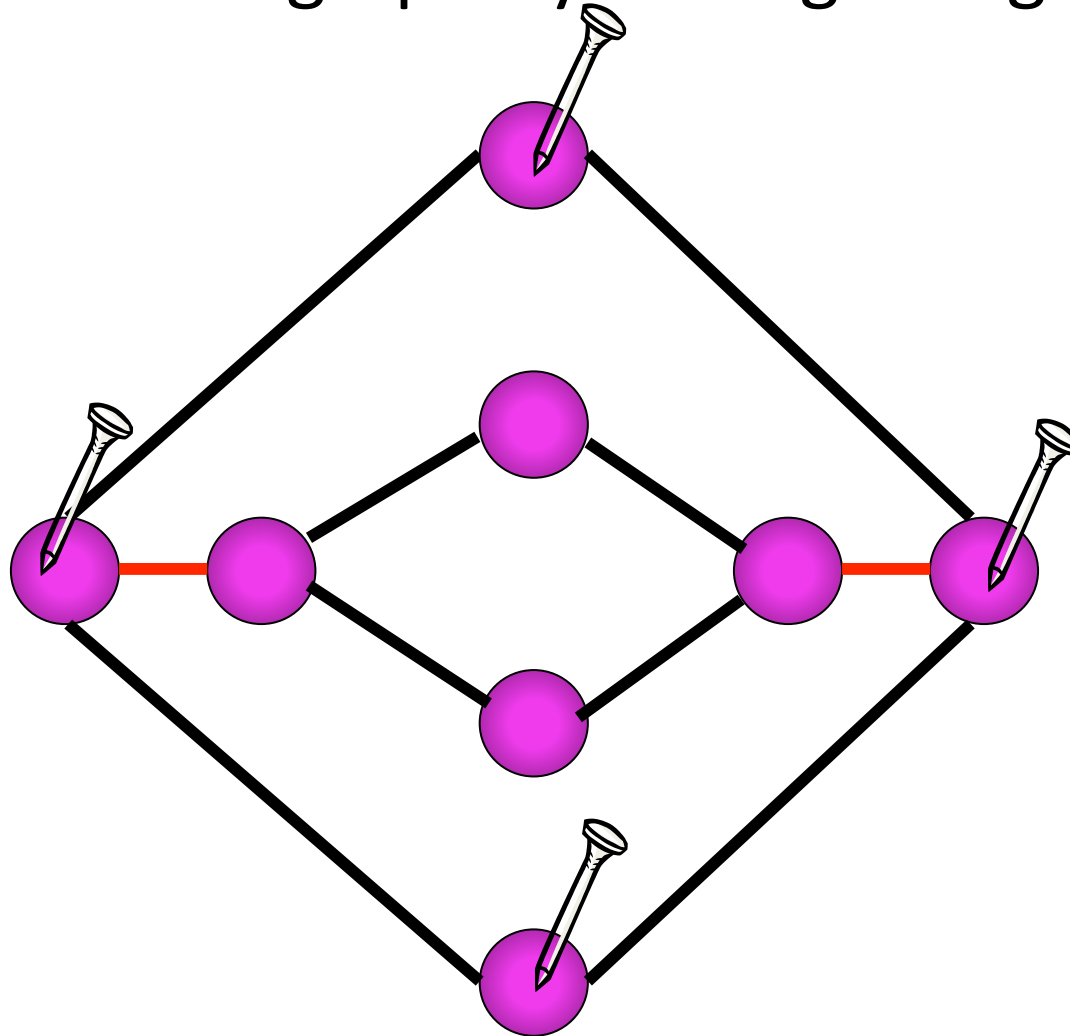
cannot break graph by cutting 2 edges



Tutte's Theorem '63

3-connected:

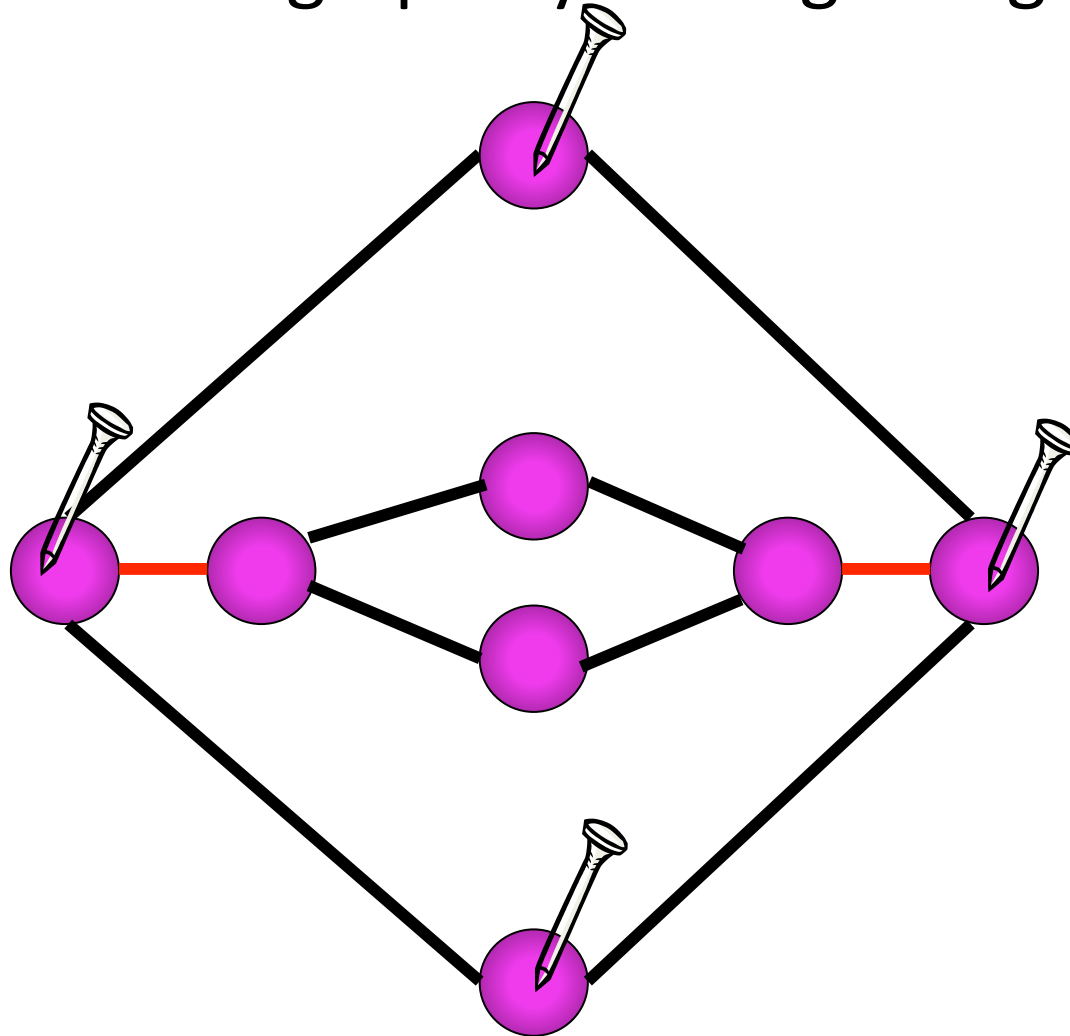
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Tutte's Theorem '63

3-connected:

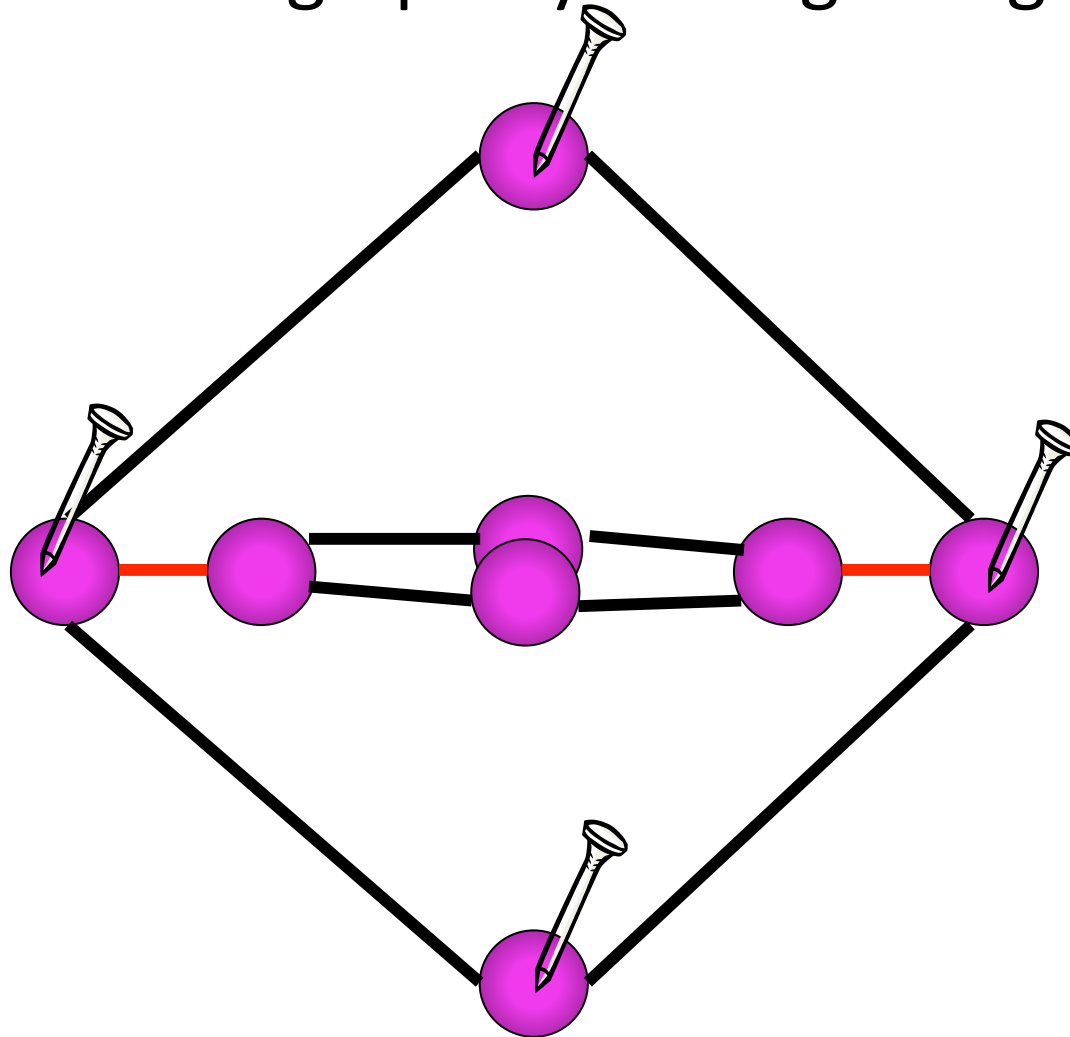
cannot break graph by cutting 2 edges



Tutte's Theorem '63

3-connected:

cannot break graph by cutting 2 edges

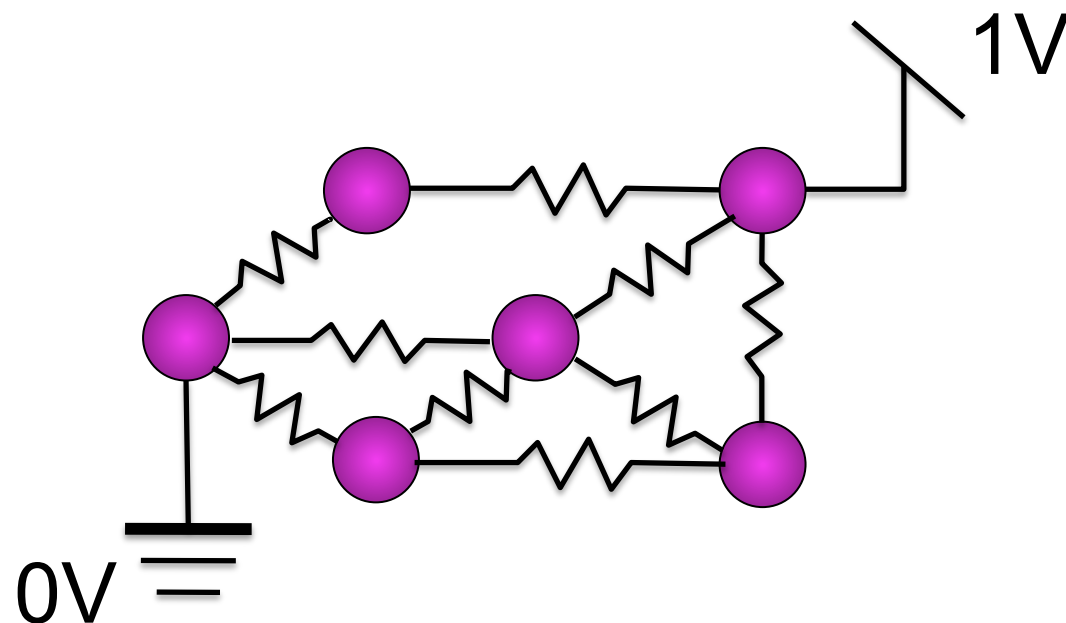


Graphs as Resistor Networks

View edges as resistors connecting vertices

Apply voltages at some vertices.

Measure induced voltages and current flow.



Graphs as Resistor Networks

View edges as resistors connecting vertices

Apply voltages at some vertices.

Measure induced voltages and current flow.

Current flow measures strength of connection between endpoints.

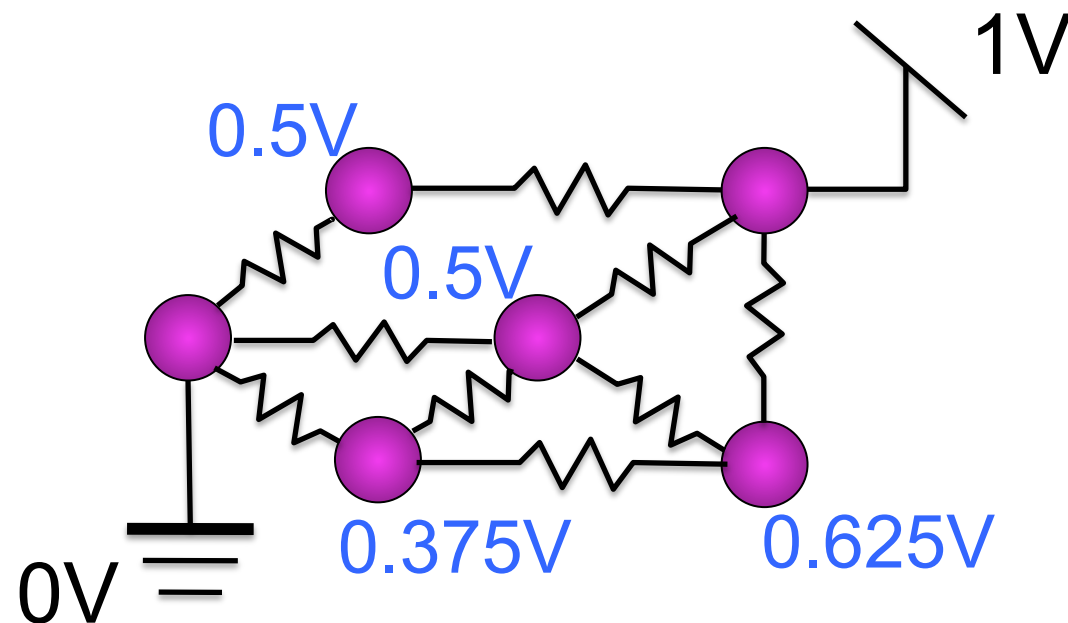
More short disjoint paths lead to higher flow.

Graphs as Resistor Networks

View edges as resistors connecting vertices

Apply voltages at some vertices.

Measure induced voltages and current flow.



Graphs as Resistor Networks

View edges as resistors connecting vertices

Apply voltages at some vertices.

Measure induced voltages and current flow.

Induced voltages minimize

$$\sum_{(a,b) \in E} (v(a) - v(b))^2$$

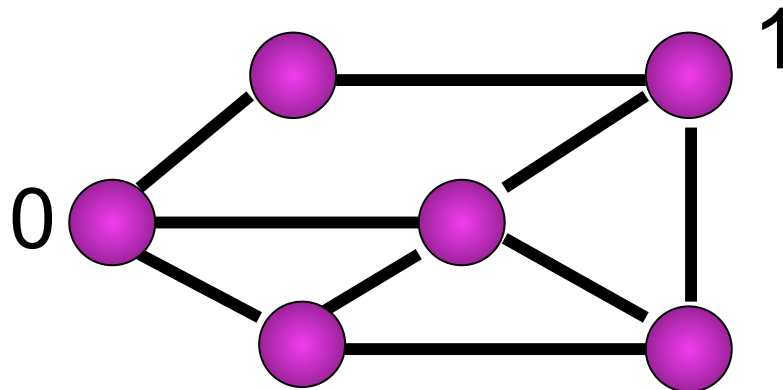
Subject to fixed voltages (by battery)

Learning on Graphs [Zhu-Ghahramani-Lafferty '03]

Infer values of a function at all vertices
from known values at a few vertices.

Minimize
$$\sum_{(a,b) \in E} (x(a) - x(b))^2$$

Subject to known values

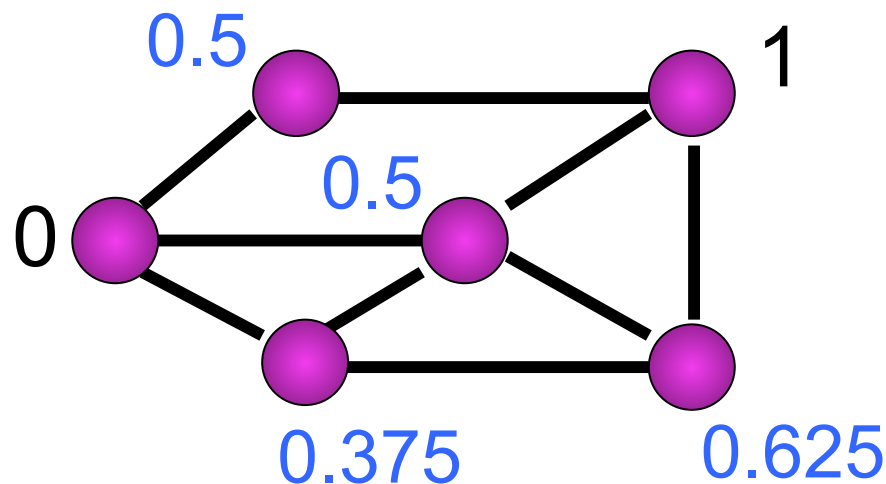


Learning on Graphs [Zhu-Ghahramani-Lafferty '03]

Infer values of a function at all vertices
from known values at a few vertices.

Minimize $\sum_{(a,b) \in E} (x(a) - x(b))^2$

Subject to known values



The Laplacian quadratic form

$$\sum_{(a,b) \in E} (x(a) - x(b))^2$$

The Laplacian matrix of a graph

$$x^T \underline{L}x = \sum_{(a,b) \in E} (x(a) - x(b))^2$$

The Laplacian matrix of a graph

$$x^T \underline{L}x = \sum_{(a,b) \in E} (x(a) - x(b))^2$$

To minimize subject to boundary constraints,
set derivative to zero.

Solve equation of form

$$Lx = b$$

Weighted Graphs

Edge (a, b) assigned a non-negative real weight
 $w_{a,b} \in \mathbb{R}$ measuring
strength of connection
spring constant
1/resistance

$$x^T L x = \sum_{(a,b) \in E} w_{a,b} (x(a) - x(b))^2$$

Weighted Graphs

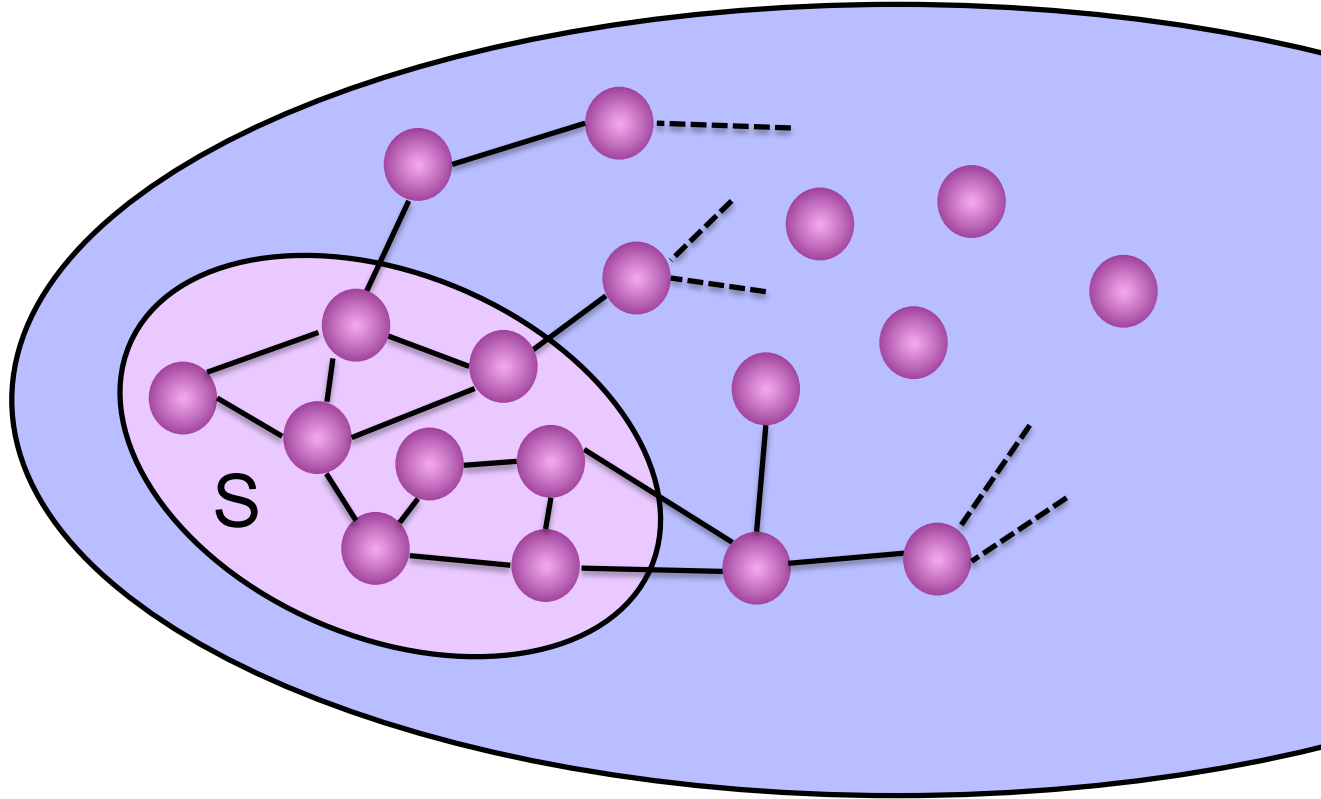
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I'll show the matrix entries tomorrow

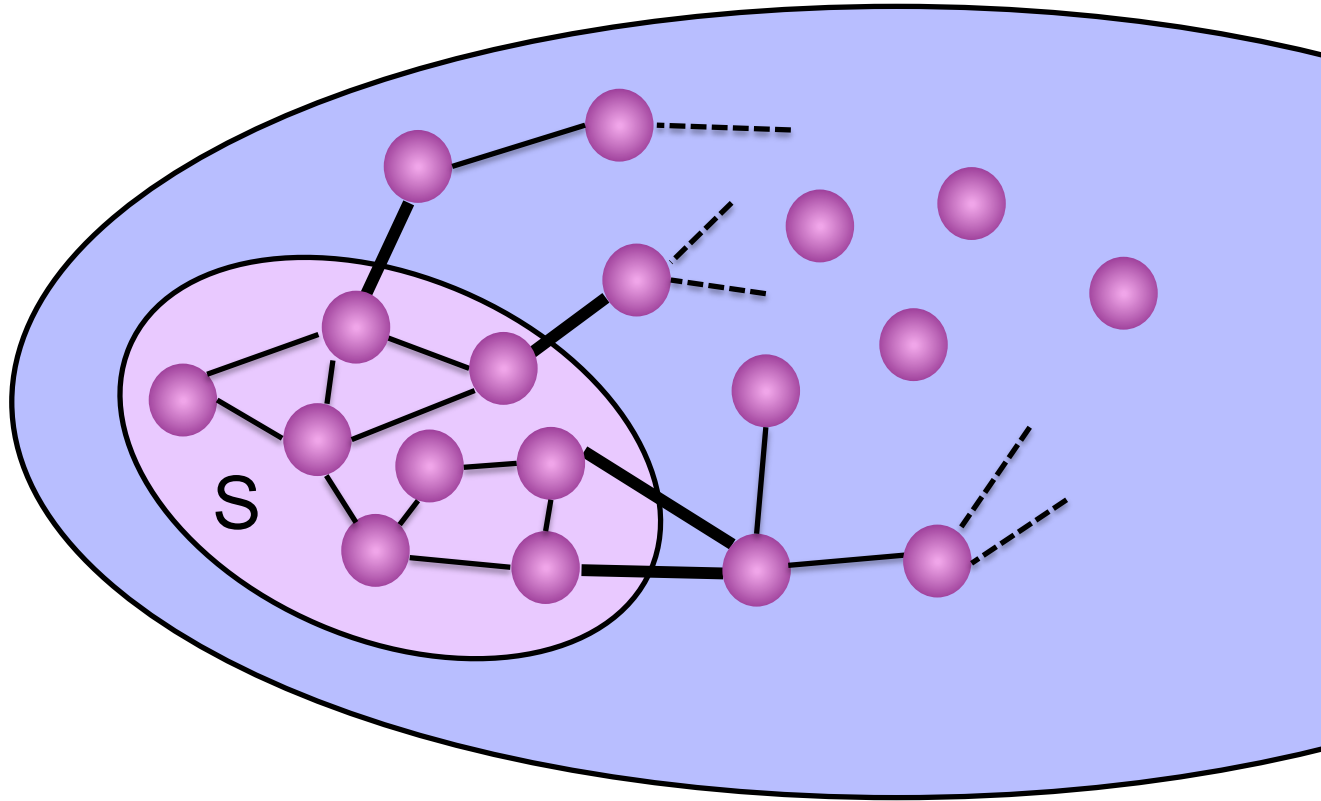
Measuring boundaries of sets

Boundary: edges leaving a set



Measuring boundaries of sets

Boundary: edges leaving a set

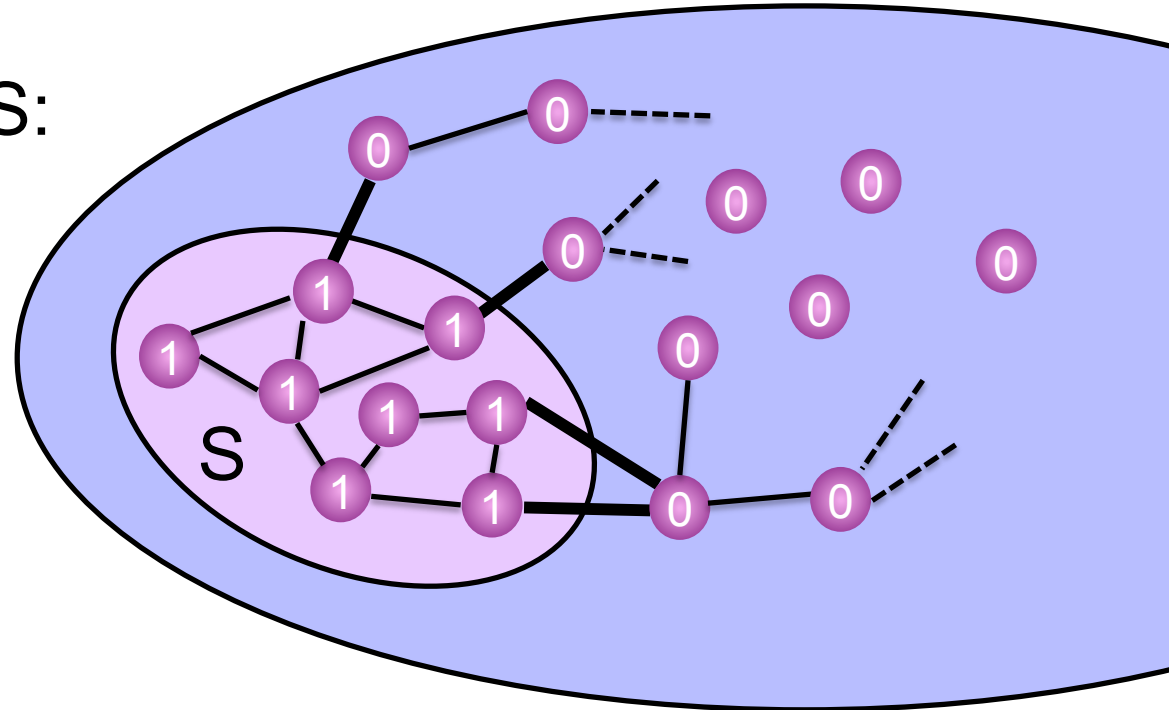


Measuring boundaries of sets

Boundary: edges leaving a set

Characteristic Vector of S :

$$x(a) = \begin{cases} 1 & a \text{ in } S \\ 0 & a \text{ not in } S \end{cases}$$

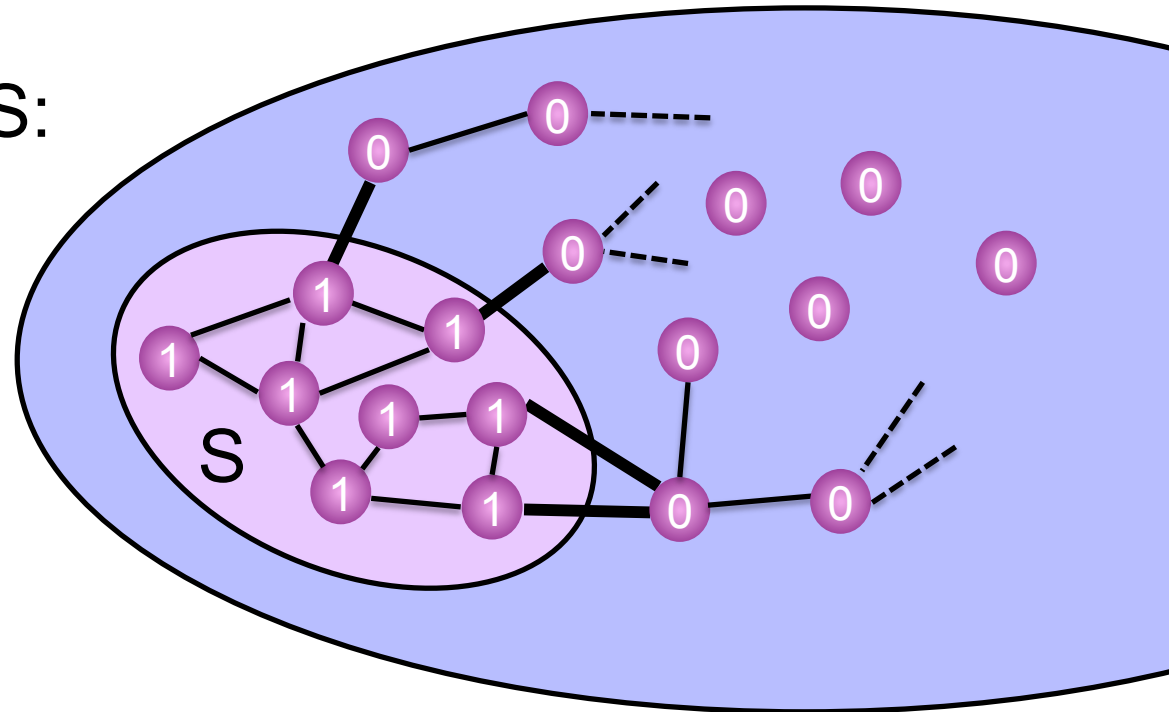


Measuring boundaries of sets

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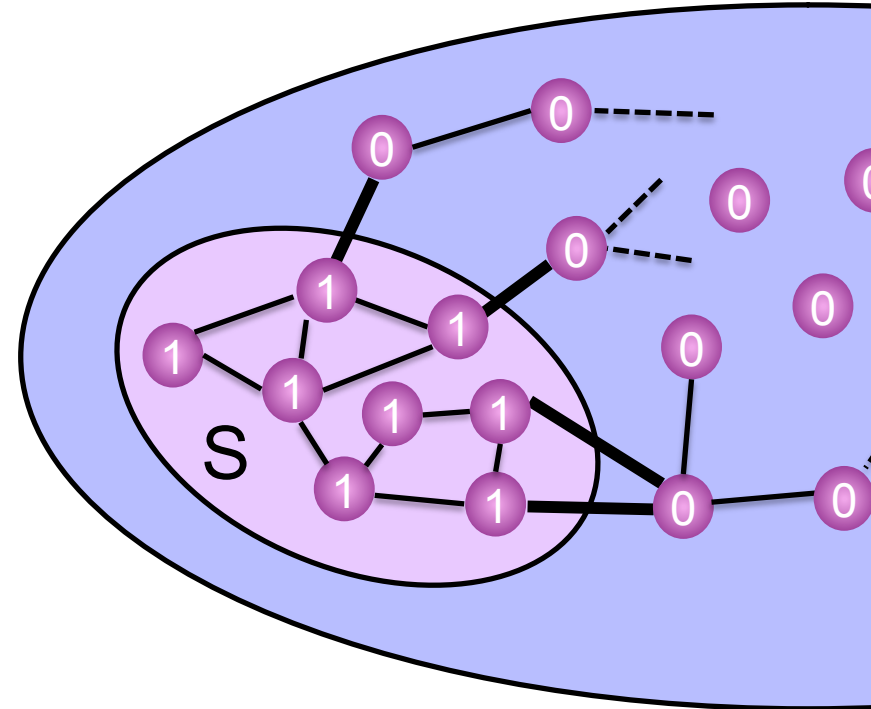
$$x^T L x = \sum_{(a,b) \in E} (x(a) - x(b))^2 = |\text{boundary}(S)|$$

Cluster Quality

$$\frac{\text{Number of edges leaving } S}{\text{Size of } S}$$

$$= \frac{|\text{boundary}(S)|}{|S|}$$

$$\stackrel{\text{def}}{=} \Phi(S) \quad (\text{sparsity})$$



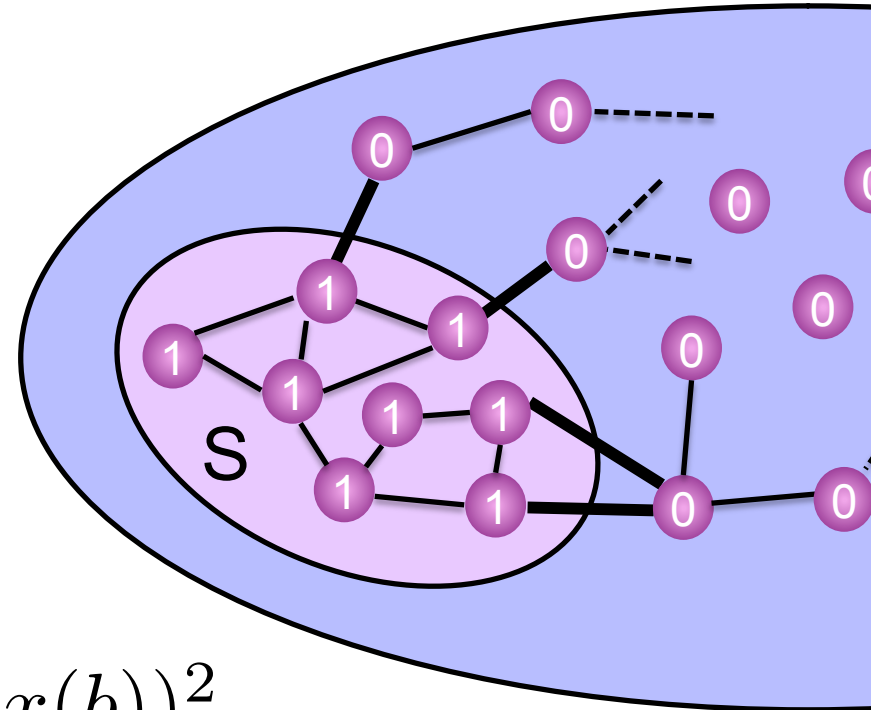
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$$= \frac{x^T L x}{x^T x} = \frac{\sum_{(a,b) \in E} (x(a) - x(b))^2}{\sum_a x(a)^2}$$



The Rayleigh Quotient of x with respect to L

Spectral Graph Theory

A n -by- n symmetric matrix has n
real eigenvalues $\lambda_1 \leq \lambda_2 \cdots \leq \lambda_n$
and eigenvectors v_1, \dots, v_n such that

$$Lv_i = \lambda_i v_i$$

Spectral Graph Theory

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These eigenvalues and eigenvectors tell us
a lot about a graph!

Theorems

Algorithms

Heuristics

The Rayleigh Quotient and Eigenvalues

A n -by- n symmetric matrix has n
real eigenvalues $\lambda_1 \leq \lambda_2 \cdots \leq \lambda_n$
and eigenvectors v_1, \dots, v_n such that

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Courant-Fischer Theorem:

$$\lambda_1 = \min_{x \neq 0} \frac{x^T L x}{x^T x} \quad v_1 = \arg \min_{x \neq 0} \frac{x^T L x}{x^T x}$$

The Courant Fischer Theorem

$$\lambda_1 = \min_{x \neq 0} \frac{x^T L x}{x^T x}$$

$$v_1 = \arg \min_{x \neq 0} \frac{x^T L x}{x^T x}$$

$$\lambda_2 = \min_{x \perp v_1} \frac{x^T L x}{x^T x}$$

$$v_2 = \arg \min_{x \perp v_1} \frac{x^T L x}{x^T x}$$

The Courant Fischer Theorem

$$\lambda_1 = \min_{x \neq 0} \frac{x^T L x}{x^T x} \quad v_1 = \arg \min_{x \neq 0} \frac{x^T L x}{x^T x}$$

$$\lambda_2 = \min_{x \perp v_1} \frac{x^T L x}{x^T x} \quad v_2 = \arg \min_{x \perp v_1} \frac{x^T L x}{x^T x}$$

$$\lambda_k = \min_{x \perp v_1, \dots, v_{k-1}} \frac{x^T L x}{x^T x}$$

$$v_k = \arg \min_{x \perp v_1, \dots, v_{k-1}} \frac{x^T L x}{x^T x}$$

The first eigenvalue

$$\begin{aligned}\lambda_1 &= \min_{x \neq 0} \frac{x^T L x}{x^T x} \\ &= \min_{x \neq 0} \frac{\sum_{(a,b) \in E} (x(a) - x(b))^2}{\|x\|^2}\end{aligned}$$

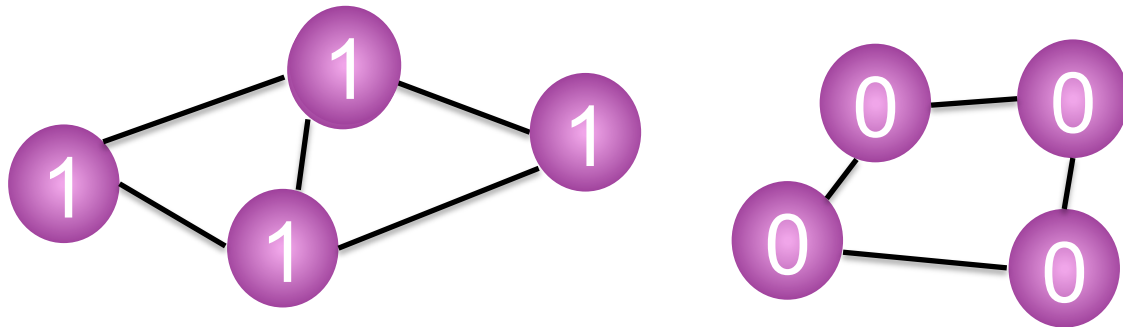
Setting $x(a) = 1$ for all a

We find $\lambda_1 = 0$ and $v_1 = \mathbf{1}$

The second eigenvalue

$\lambda_2 > 0$ if and only if G is connected

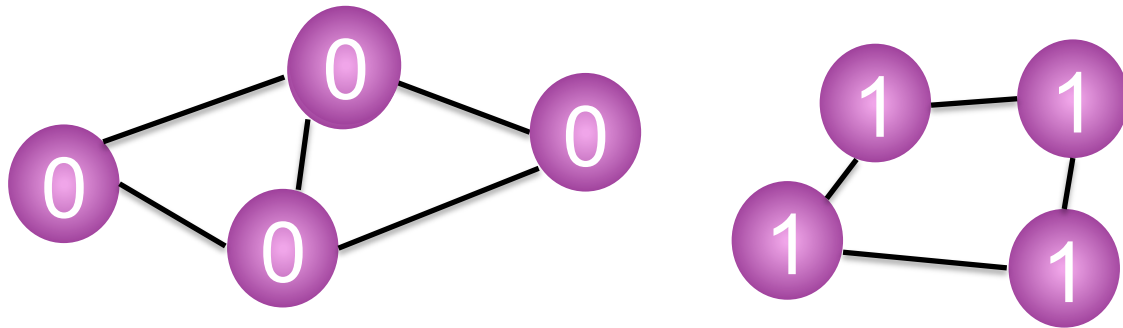
Proof: if G is not connected,
are two functions with Rayleigh quotient zero



The second eigenvalue

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The second eigenvalue

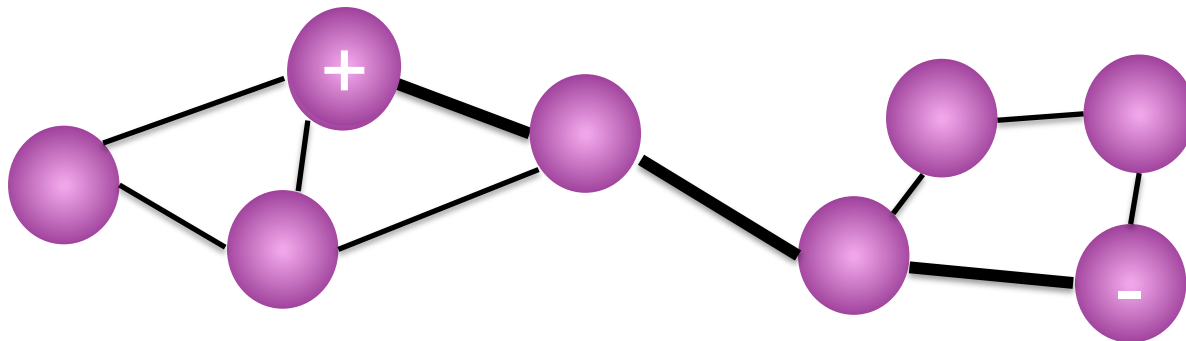
$\lambda_2 > 0$ if and only if G is connected

Proof: if G is connected,

$$x \perp \mathbf{1} \text{ means } \sum_a x(a) = 0$$

So must be an edge (a,b) for which

$$x(a) < x(b) \text{ and so } (x(a) - x(b))^2 > 0$$



The second eigenvalue

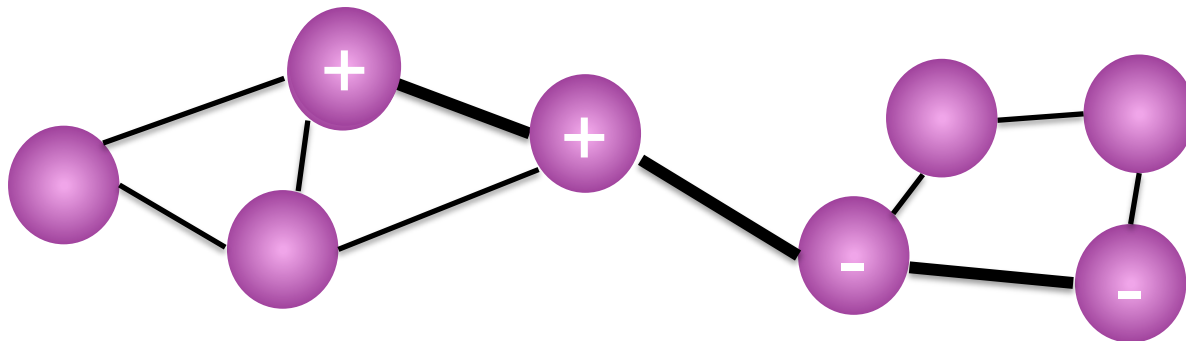
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The second eigenvalue

$\lambda_2 > 0$ if and only if G is connected

Fiedler ('73) called λ_2

“the algebraic connectivity of a graph”

The further from 0, the more connected.

Cheeger's Inequality [Cheeger '70]

[Alon-Milman '85, Jerrum-Sinclair '89, Diaconis-Stroock '91]

1. λ_2 is big if and only if G does not have good clusters.
2. If λ_2 is small, can use v_2 to find a good cluster.

Cheeger's Inequality [Cheeger '70]

[Alon-Milman '85, Jerrum-Sinclair '89, Diaconis-Stroock '91]

1. λ_2 is big if and only if G does not have good clusters.

When every vertex has d edges,

$$\lambda_2/2 \leq \min_{|S| \leq n/2} \Phi(S) \leq \sqrt{2d\lambda_2}$$

$$\Phi(S) = \frac{|\text{boundary}(S)|}{|S|}$$

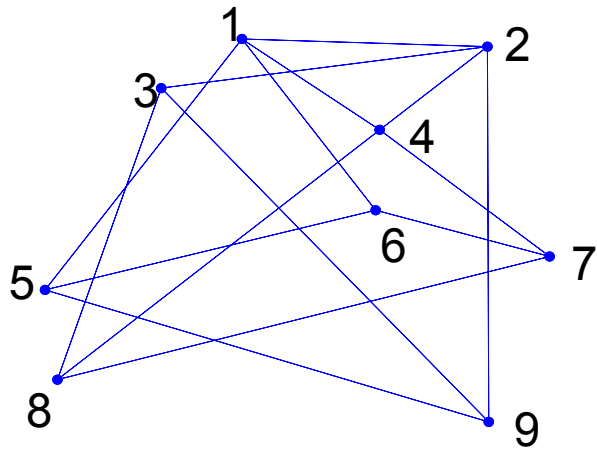
Cheeger's Inequality [Cheeger '70]

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In a moment...

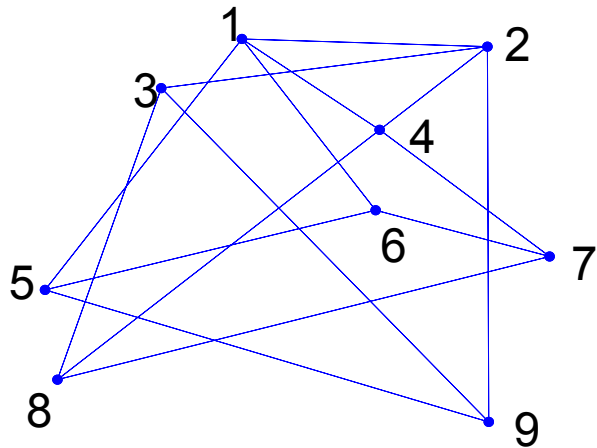
Spectral Graph Drawing [Hall '70]



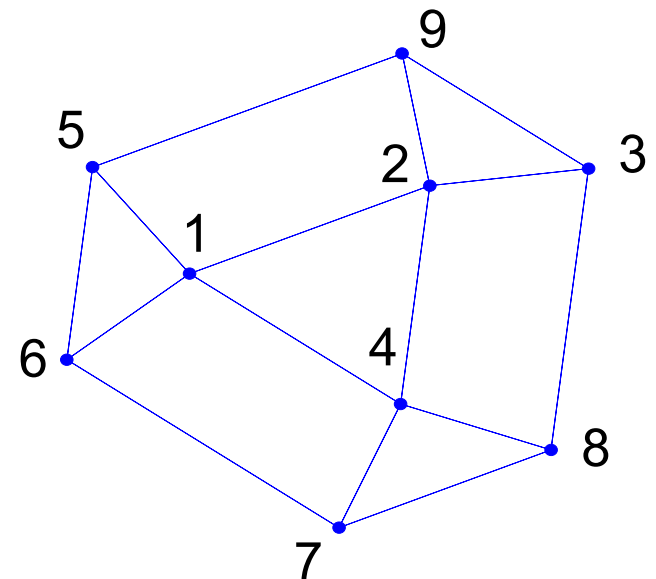
Arbitrary
Drawing

Spectral Graph Drawing [Hall '70]

Plot vertex a at $(v_2(a), v_3(a))$
draw edges as straight lines

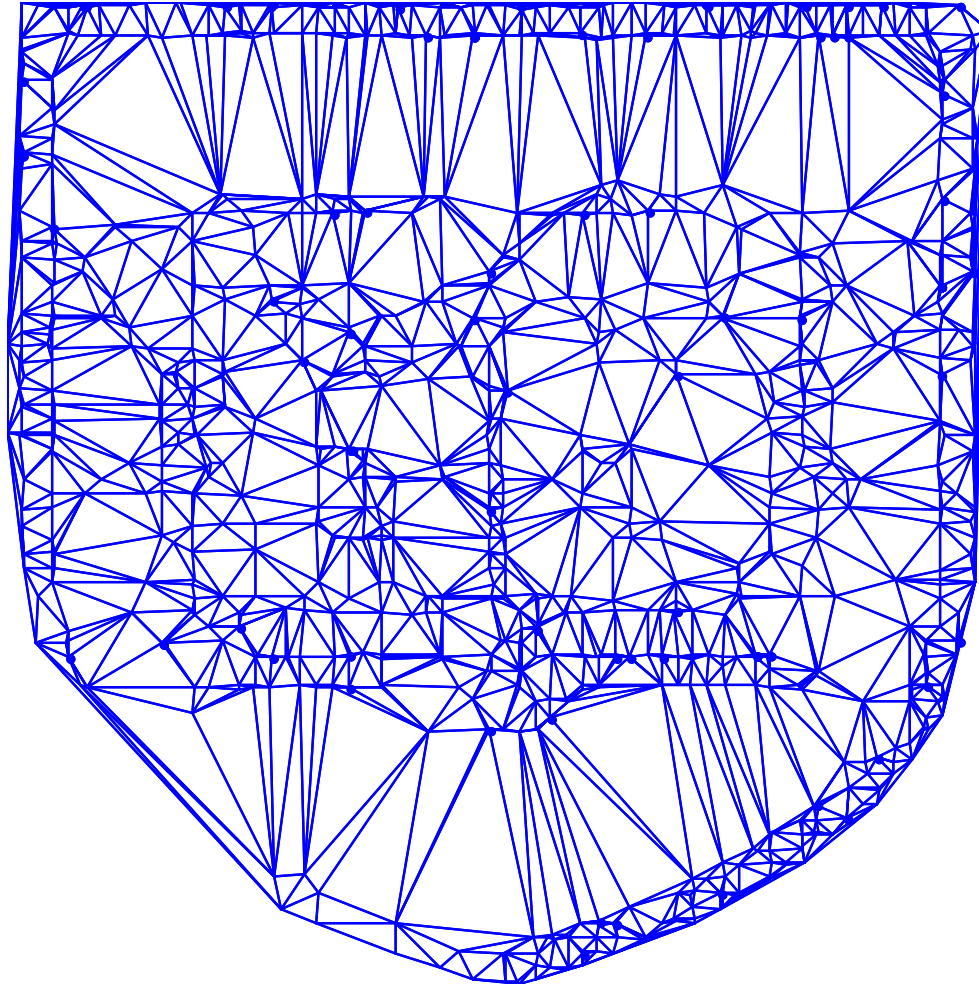


Arbitrary
Drawing

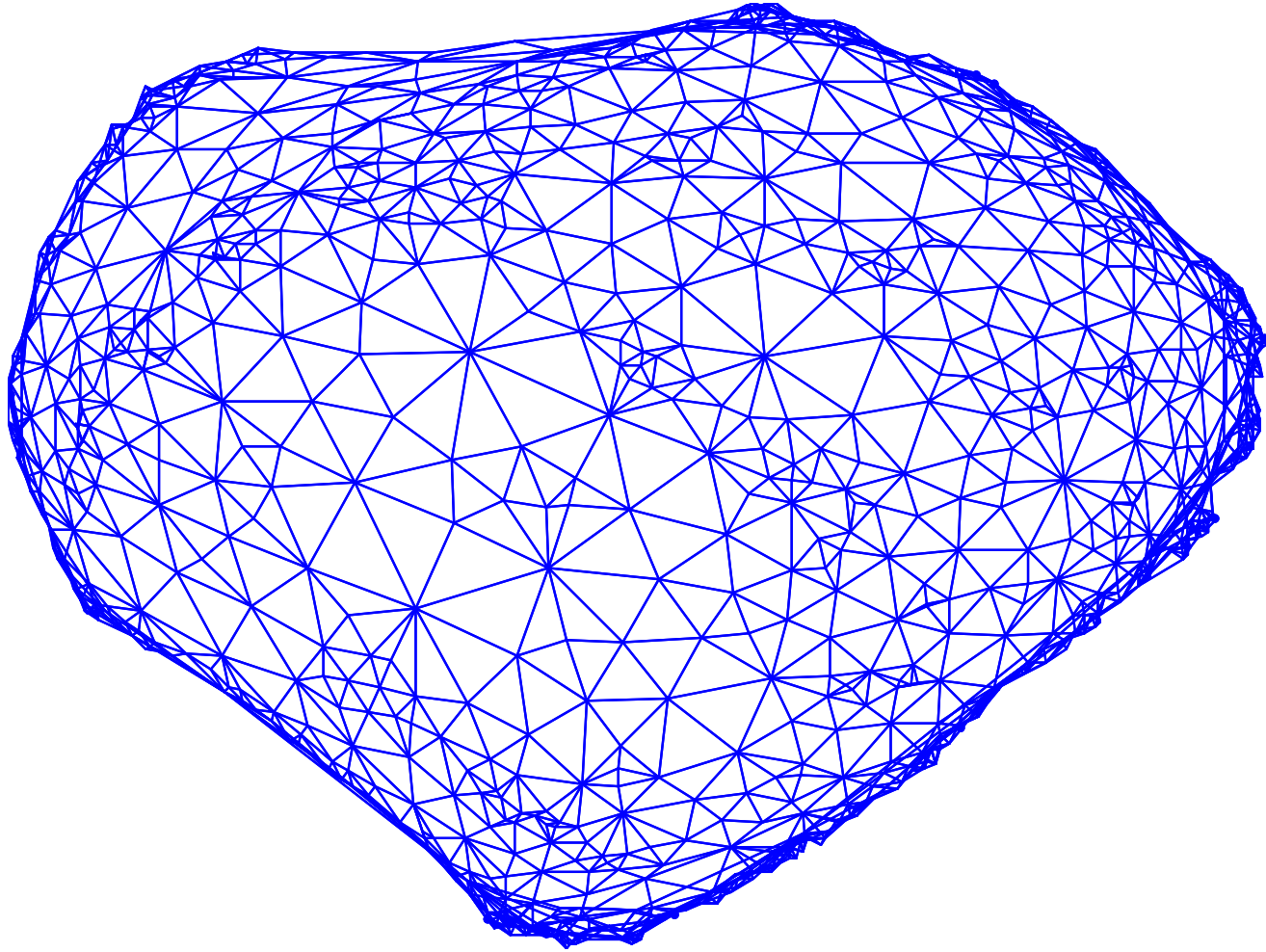


Spectral
Drawing

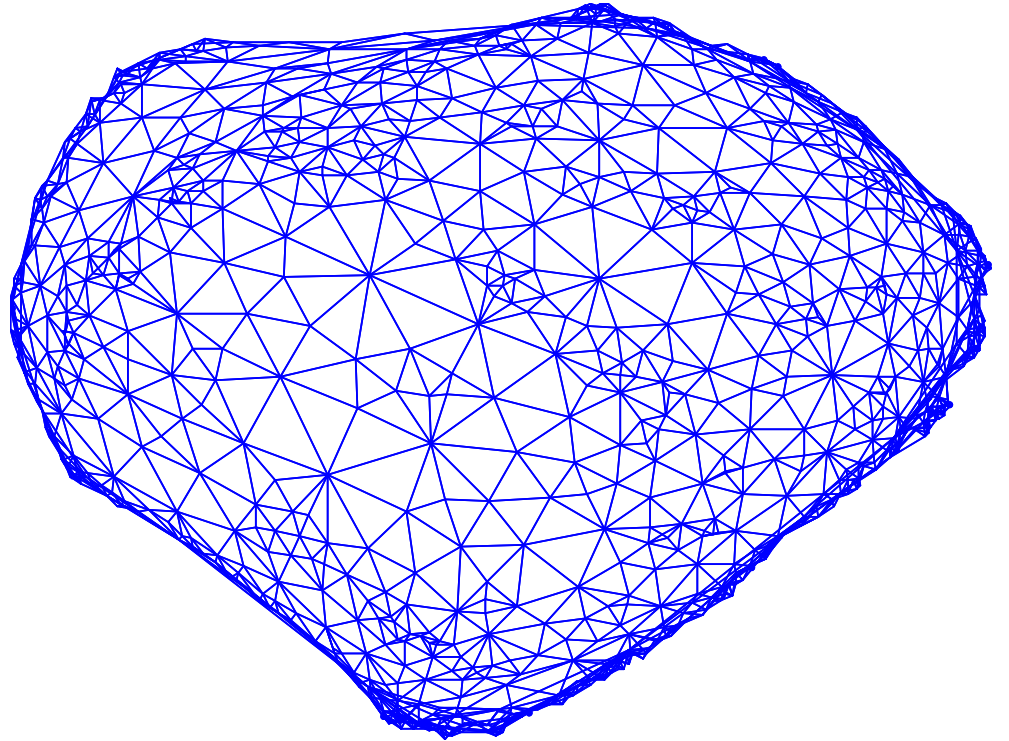
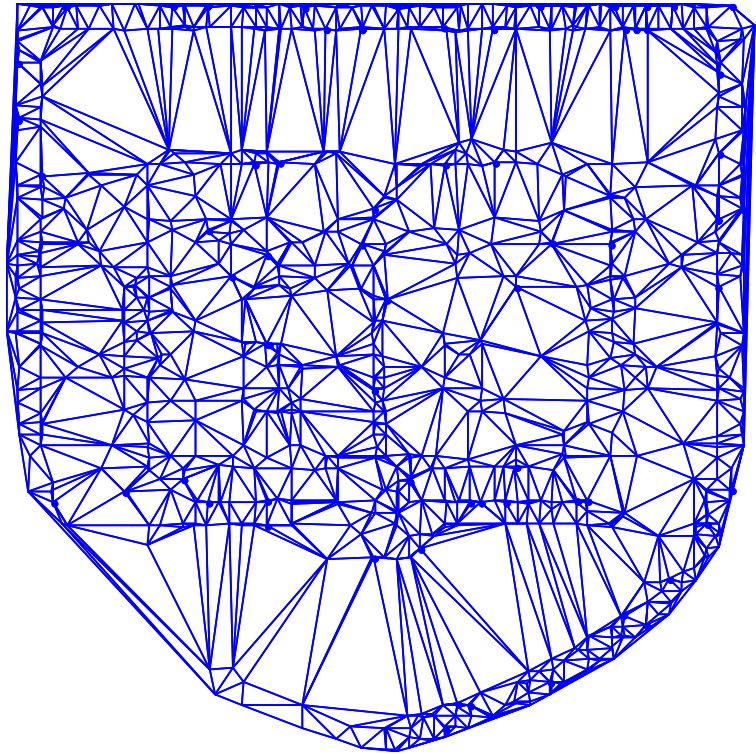
A Graph



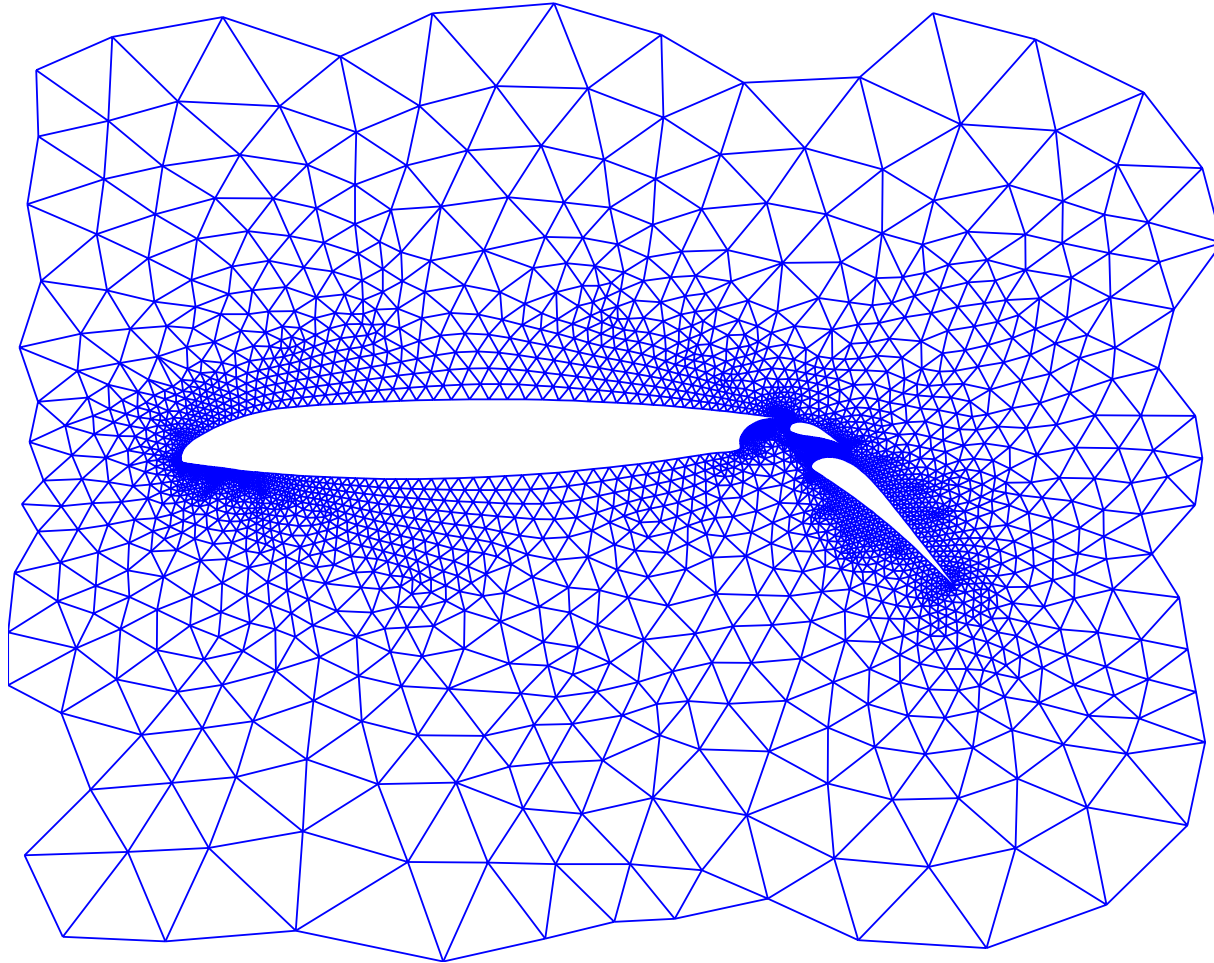
Drawing of the graph using v_2, v_3



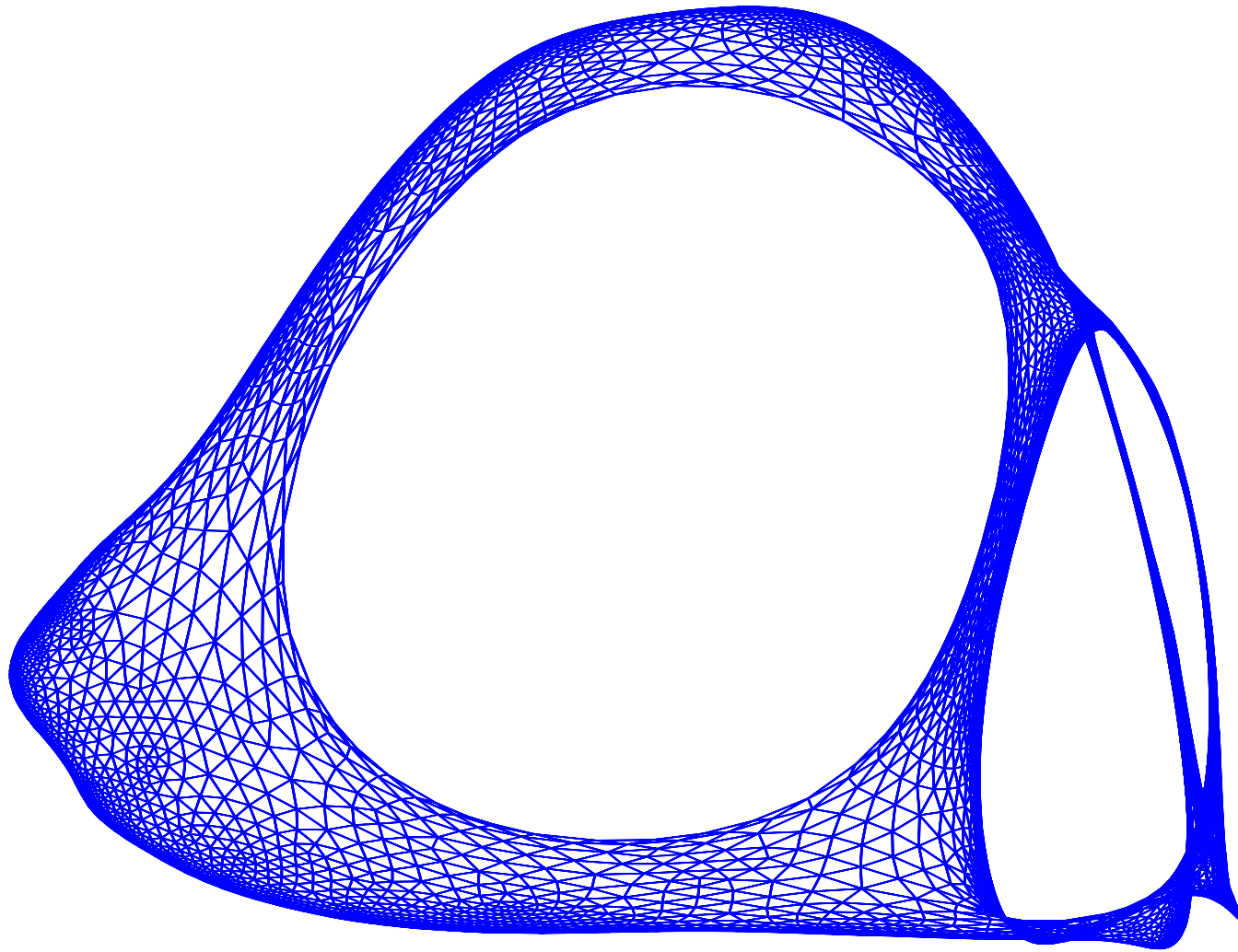
Plot vertex a at $(v_2(a), v_3(a))$



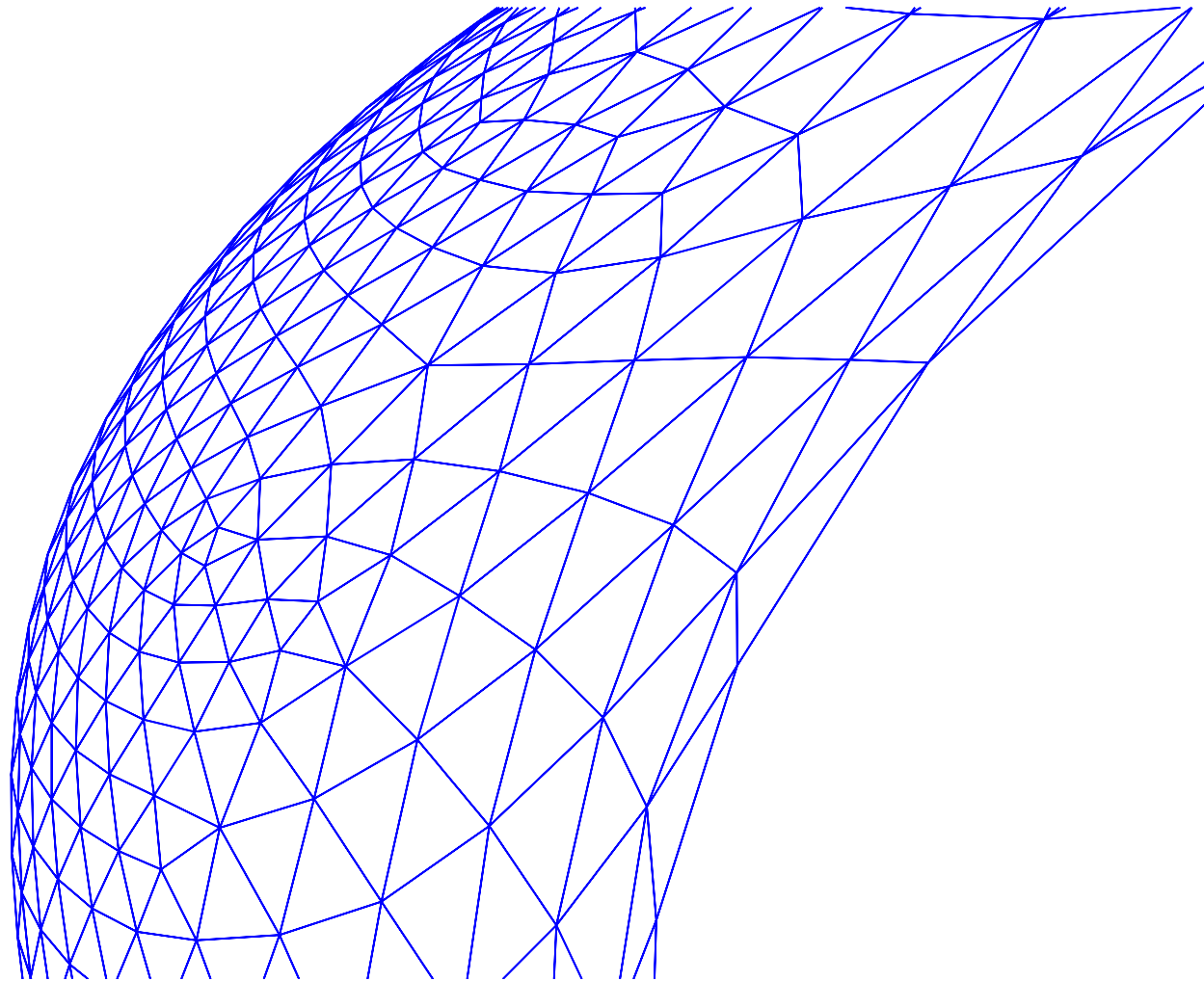
The Airfoil Graph, original coordinates



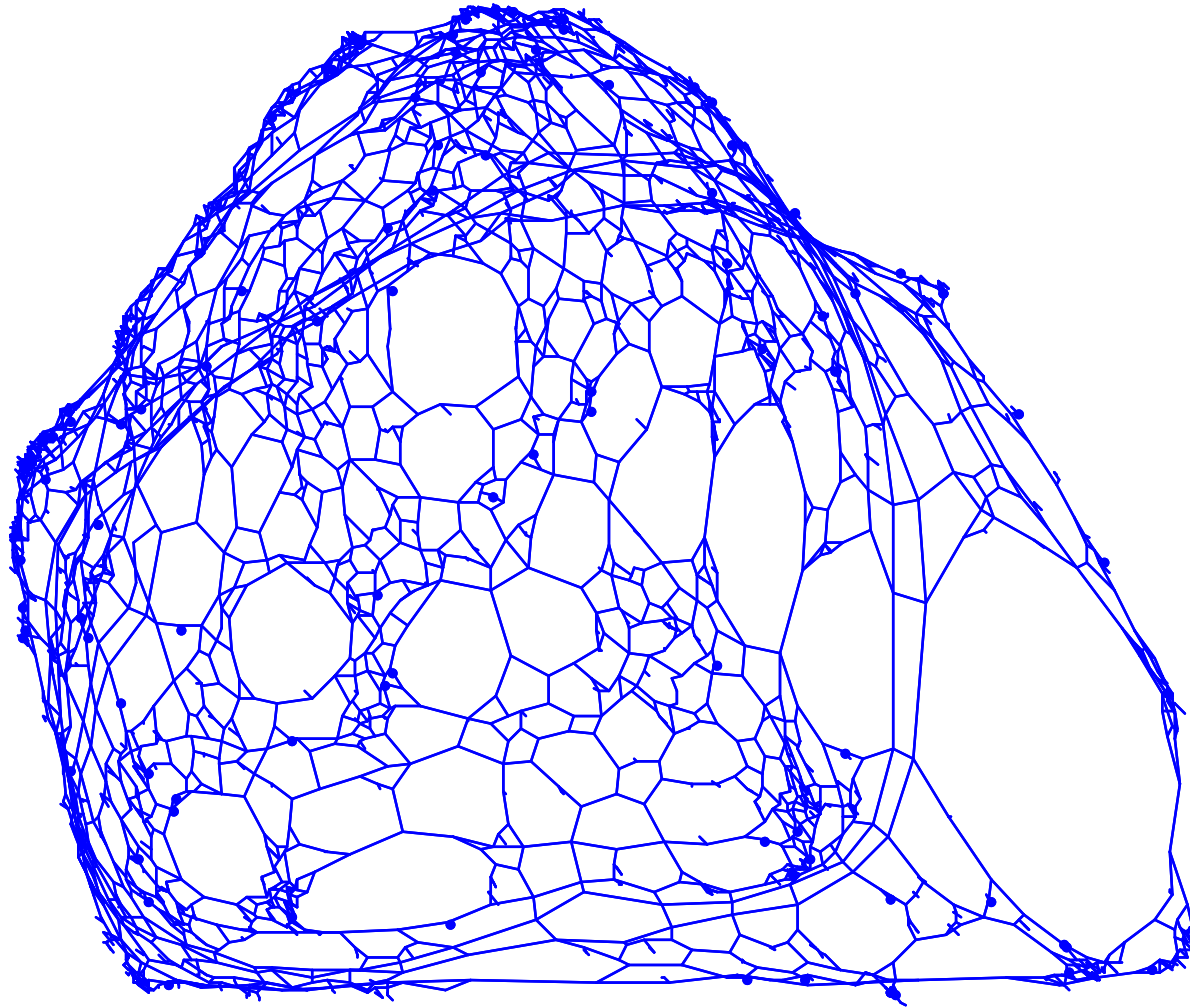
The Airfoil Graph, spectral coordinates



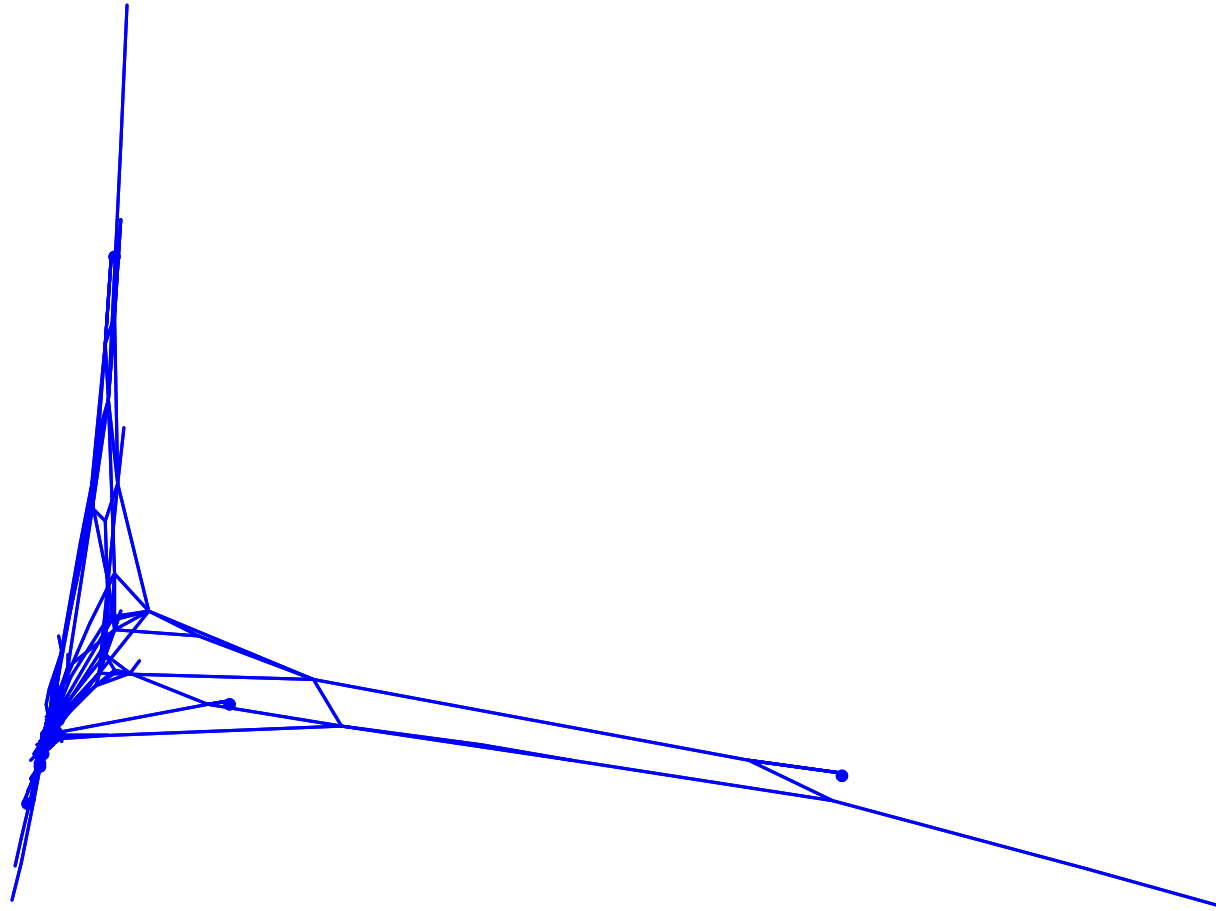
The Airfoil Graph, spectral coordinates



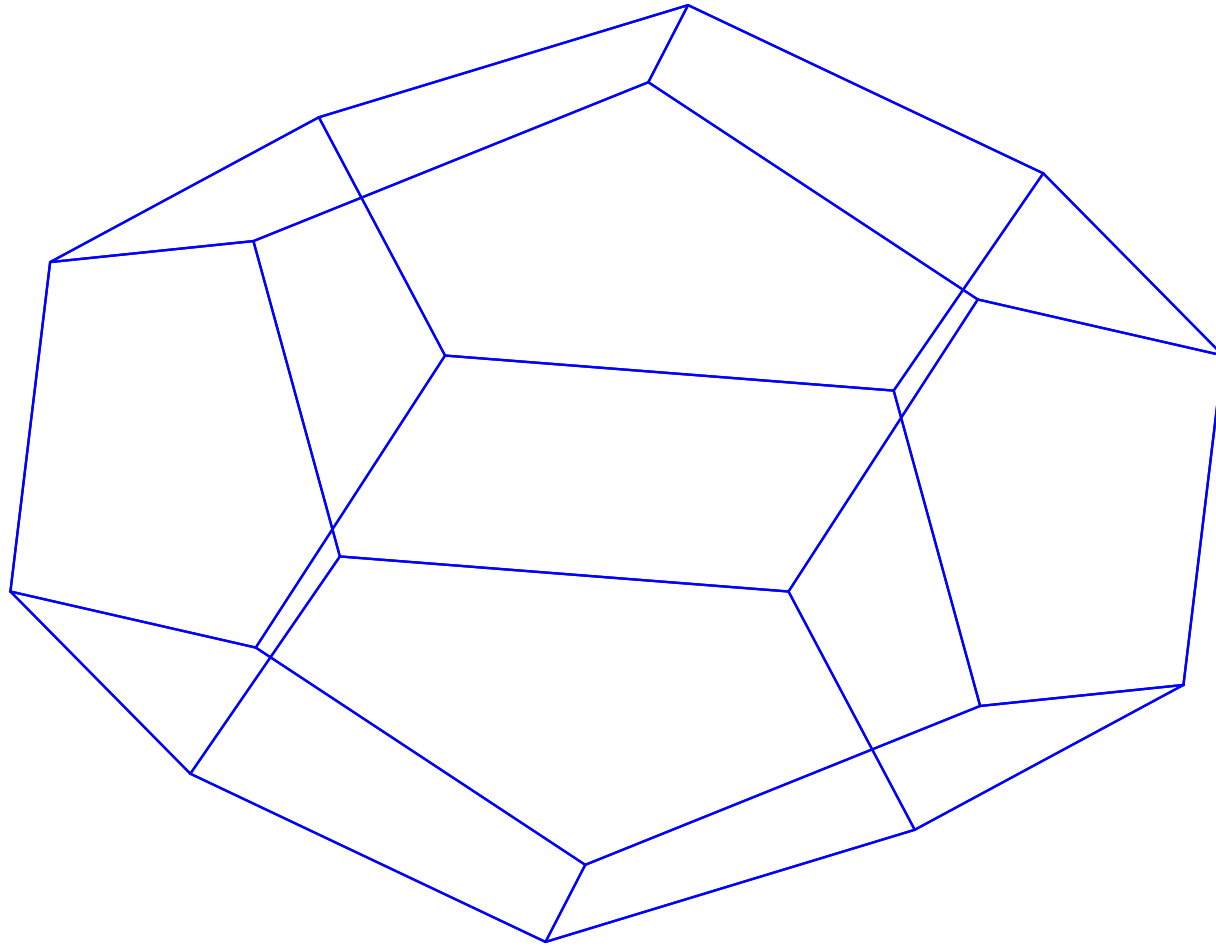
Spectral drawing of Streets in Rome



Spectral drawing of Erdos graph: edge between co-authors of papers



Dodecahedron



Best embedded by first three eigenvectors

Spectral graph drawing: Tutte justification

Condition for eigenvector $Lx = \lambda x$

Gives $\vec{x}(a) = \frac{1}{d_a - \lambda} \sum_{(a,b) \in E} \vec{x}(b)$ for all a

λ small says $\vec{x}(a)$ near average of neighbors

Spectral graph drawing: Tutte justification

Condition for eigenvector $Lx = \lambda x$

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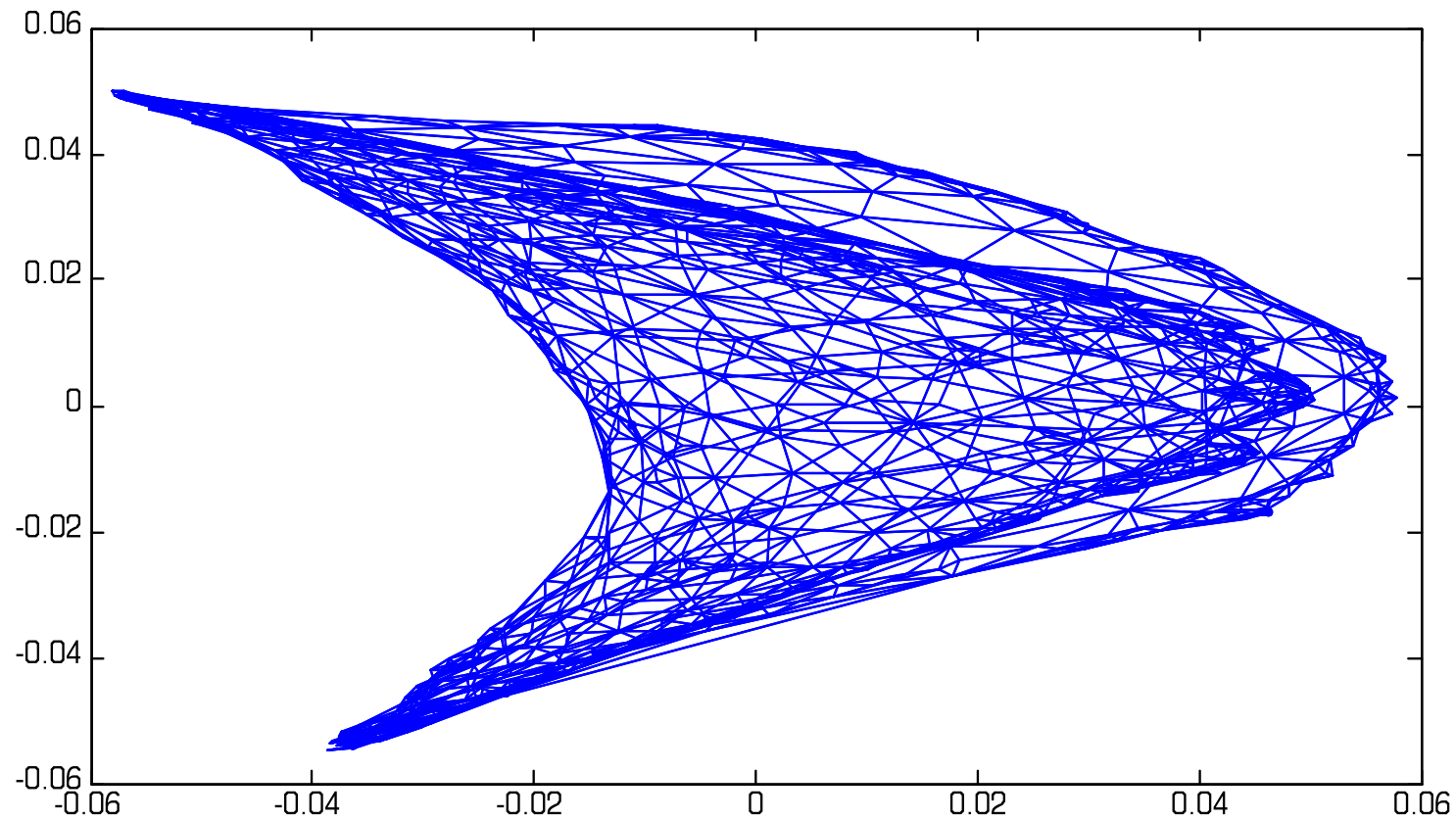
λ small says $\vec{x}(a)$ near average of neighbors

For planar graphs:

$$\lambda_2 \leq 8d/n \quad [\text{S-Teng '96}]$$

$$\lambda_3 \leq O(d/n) \quad [\text{Kelner-Lee-Price-Teng '09}]$$

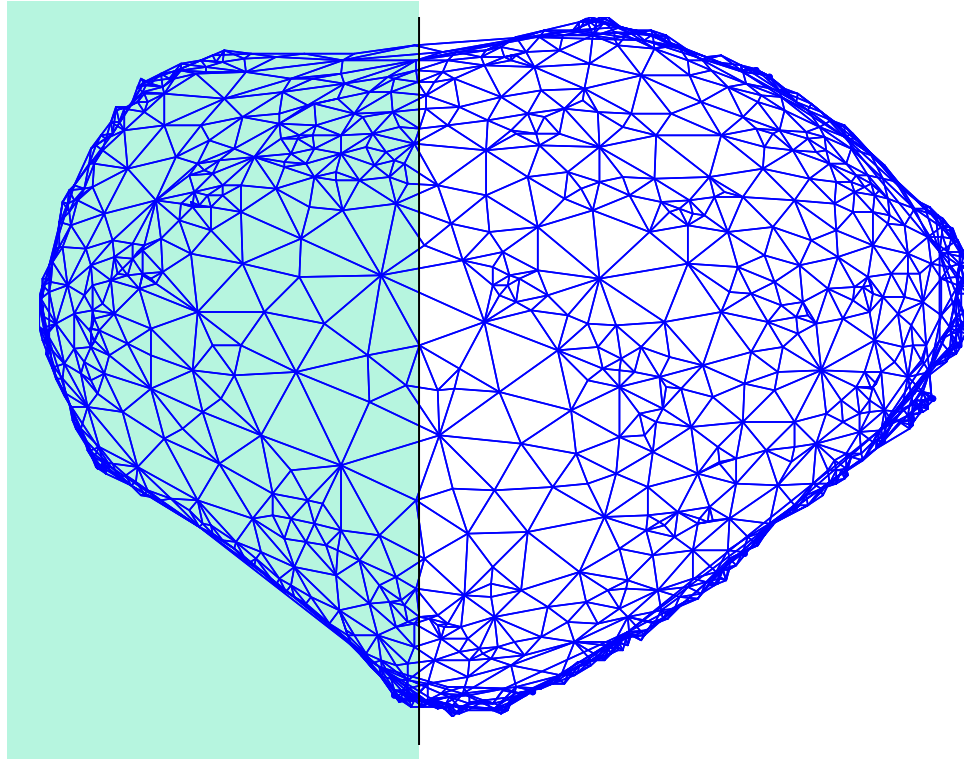
Small eigenvalues are not enough



Plot vertex a at $(v_3(a), v_4(a))$

Spectral Graph Partitioning

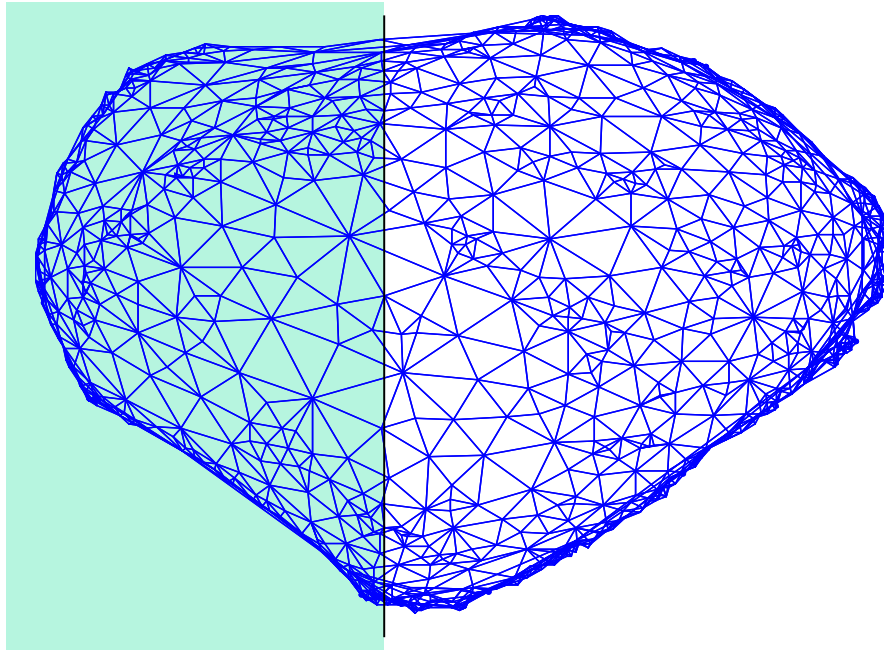
[Donath-Hoffman '72, Barnes '82, Hagen-Kahng '92]



$$S = \{a : v_2(a) \leq t\} \text{ for some } t$$

Spectral Graph Partitioning

[Donath-Hoffman '72, Barnes '82, Hagen-Kahng '92]



$$S = \{a : v_2(a) \leq t\} \text{ for some } t$$

Cheeger's Inequality says there is a t so that

$$\Phi(S) \leq \sqrt{2d\lambda_2}$$

Major topics in spectral graph theory

Graph Isomorphism:

determining if two graphs are the same

Independent sets:

large sets of vertices containing no edges

Graph Coloring:

so that edges connect different colors

Major topics in spectral graph theory

Graph Isomorphism

Independent sets

Graph Coloring

Behavior under graph transformations

Random Walks and Diffusion

PageRank and Hits

Colin de Verdière invariant

Special Graphs

- from groups

- from meshes

Machine learning

Image processing

Solving linear equations in Laplacians

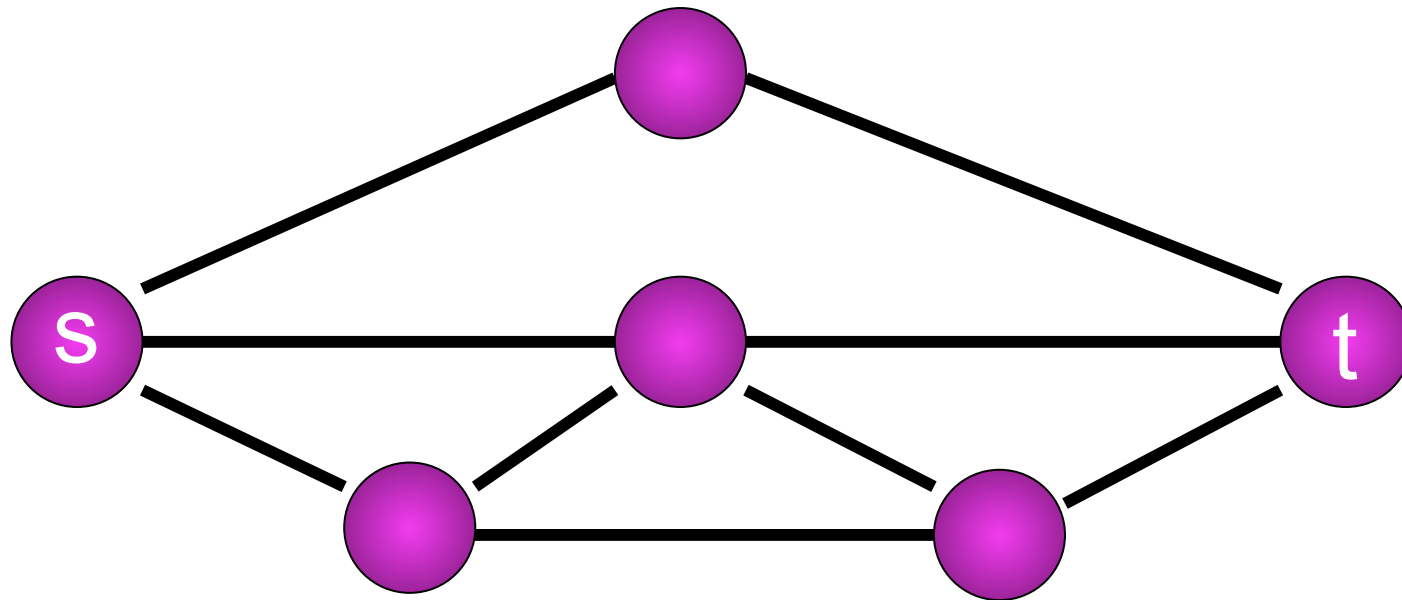
For energy minimization and
computation of eigenvectors and eigenvalues

Can do it in time nearly-linear in the
number of edges in the graph!

A powerful computational primitive.

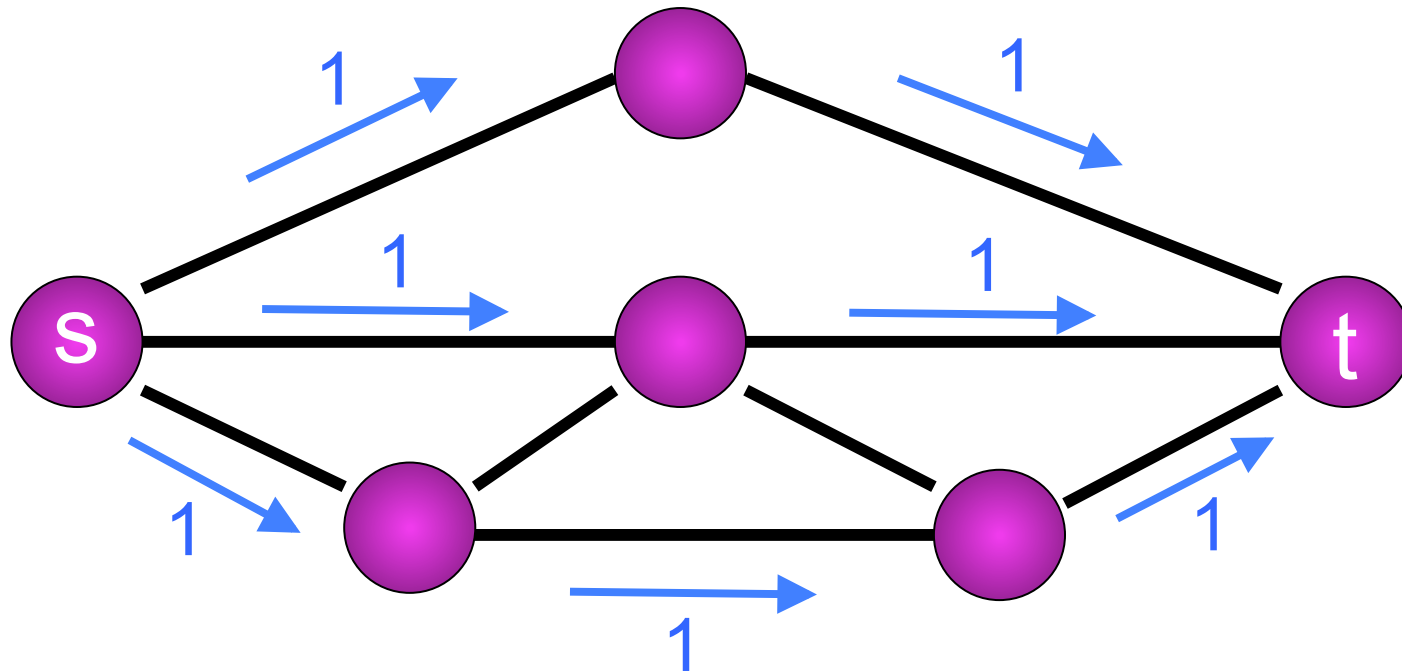
Maximum flow problem

Send as much stuff as possible from s to t.
At most one unit can go through each edge.



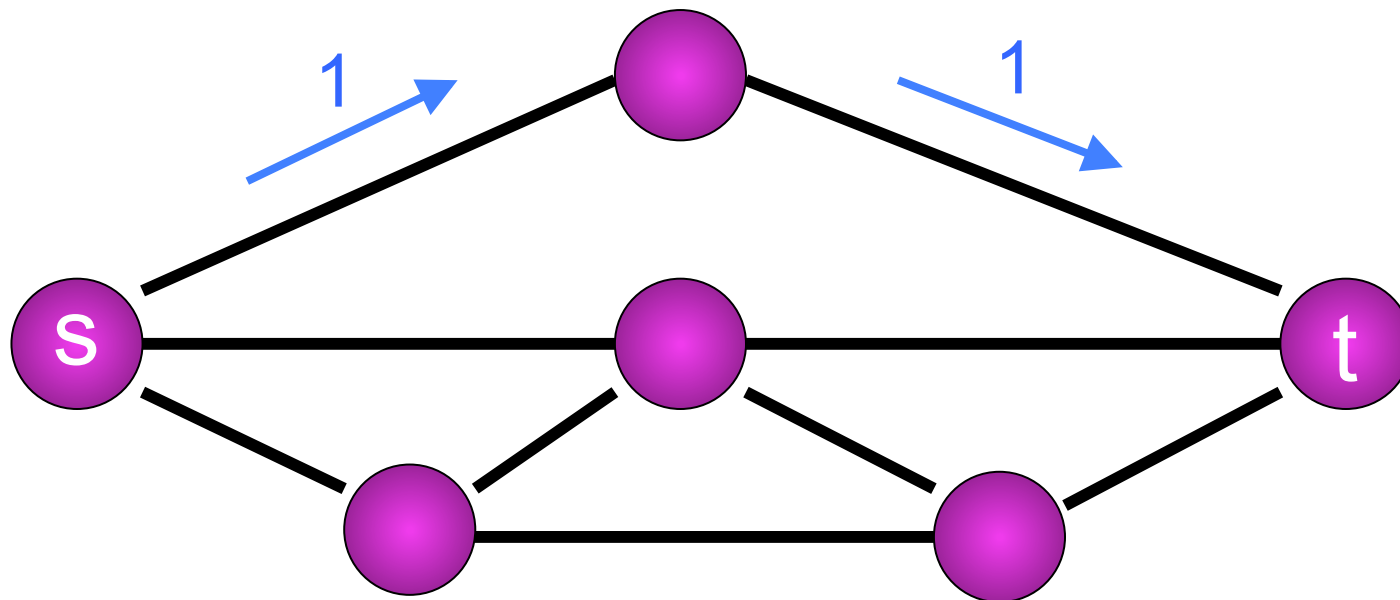
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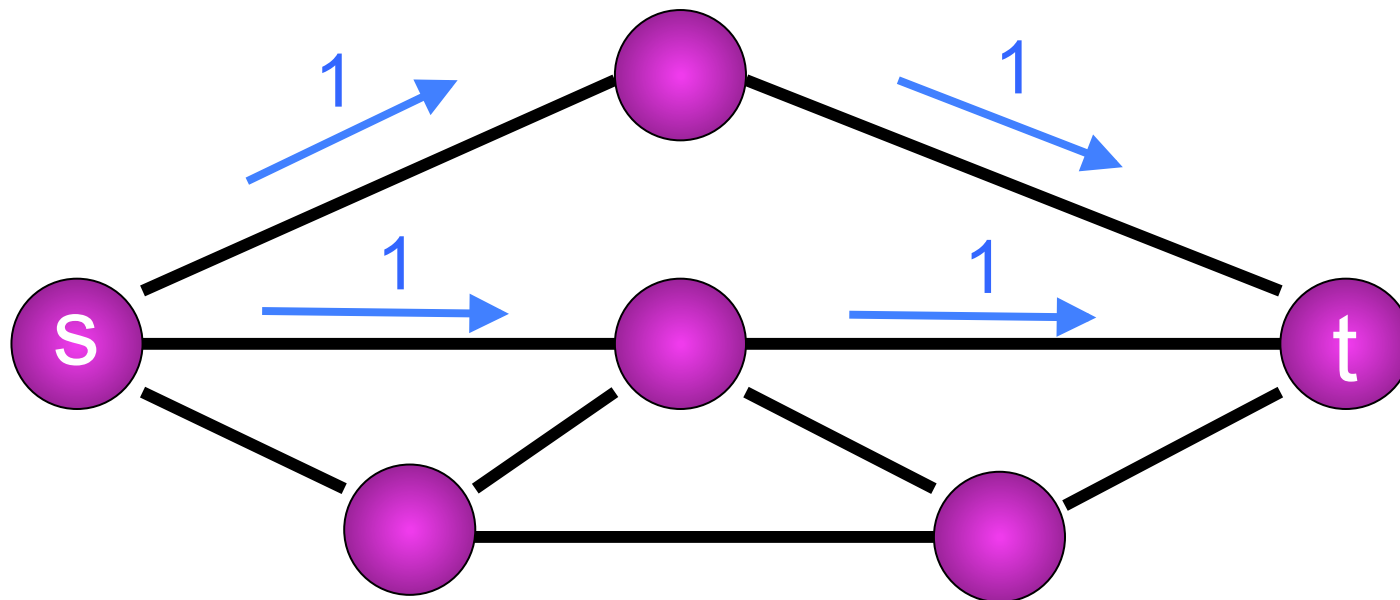
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Standard approach: incrementally add flow paths

Maximum flow problem

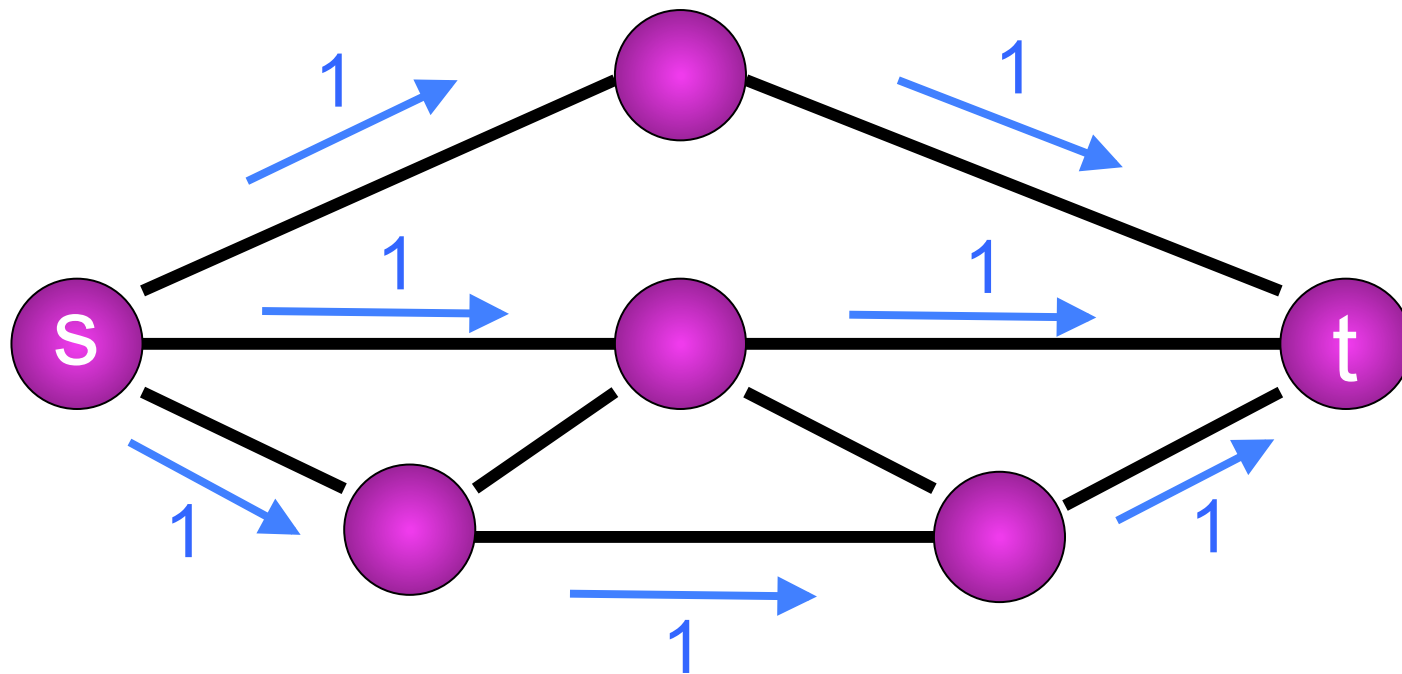
Send as much stuff as possible from s to t.
At most one unit can go through each edge.



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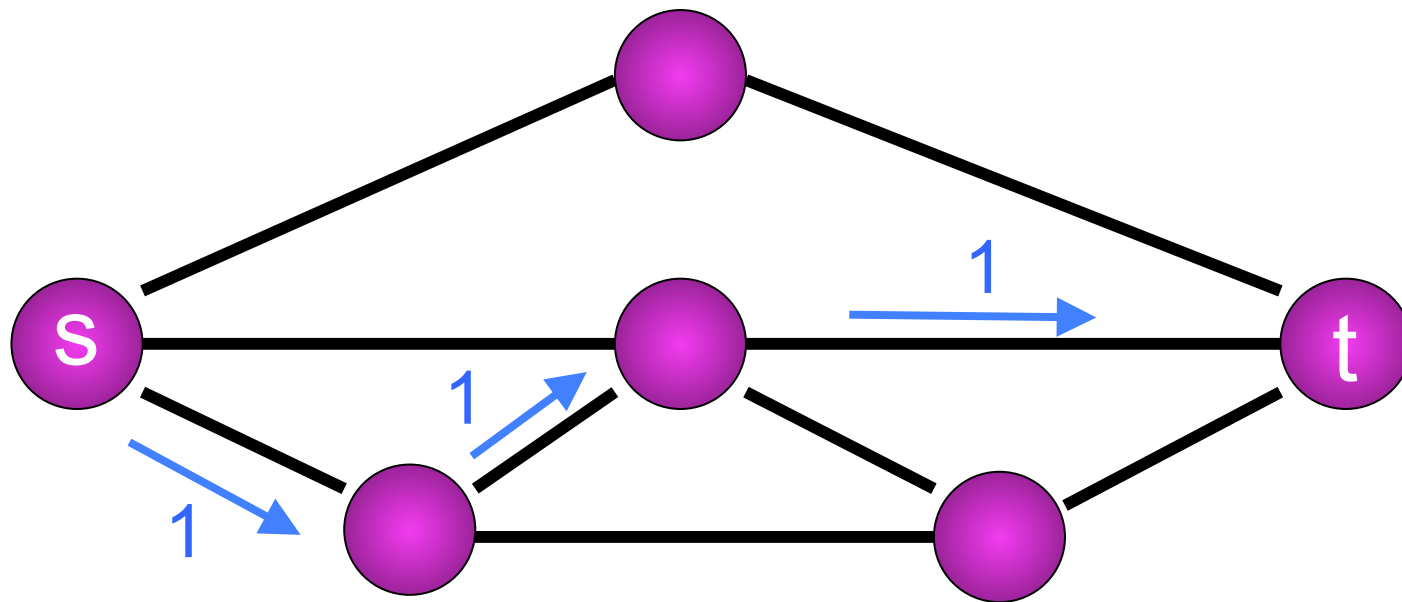
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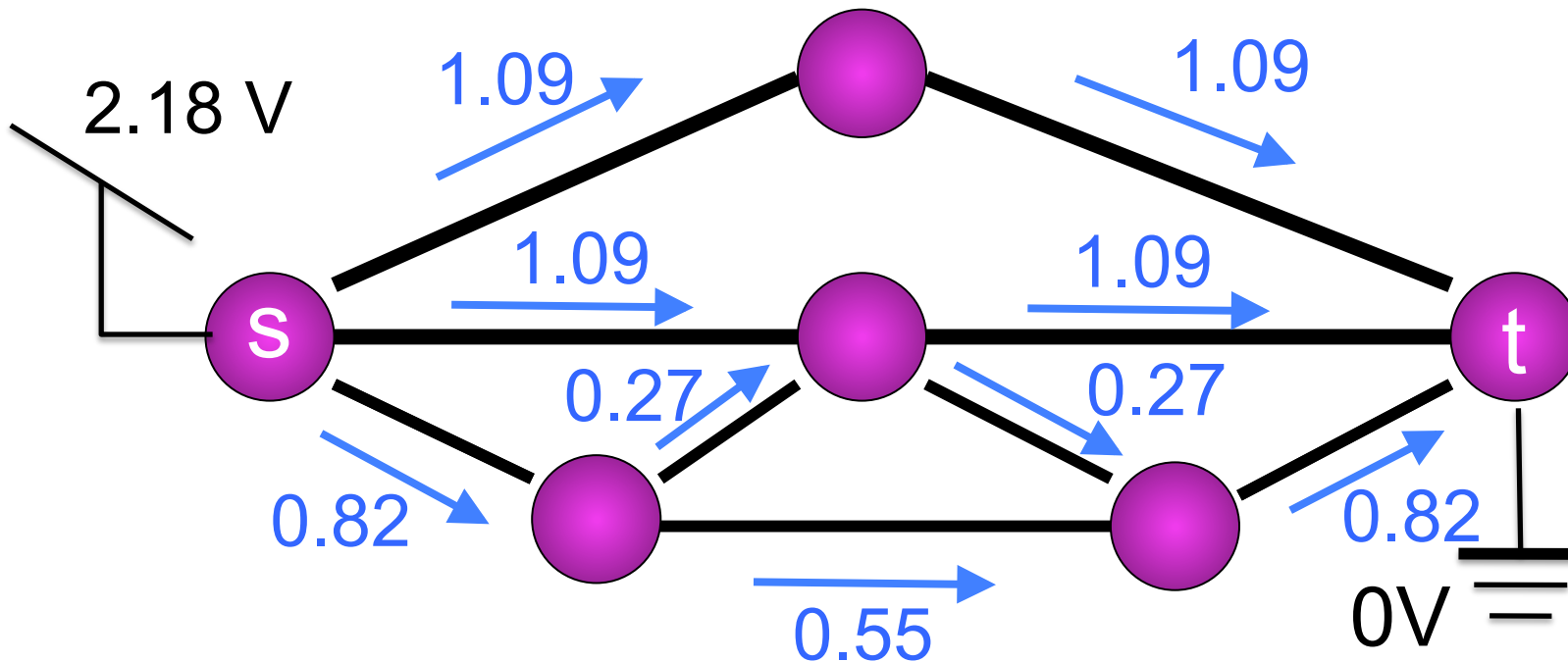


Standard approach: incrementally add flow paths
Issue: sometimes requires backtracking

Maximum flow problem, electrical approach

[Christiano-Kelner-Madry-S-Teng '11]

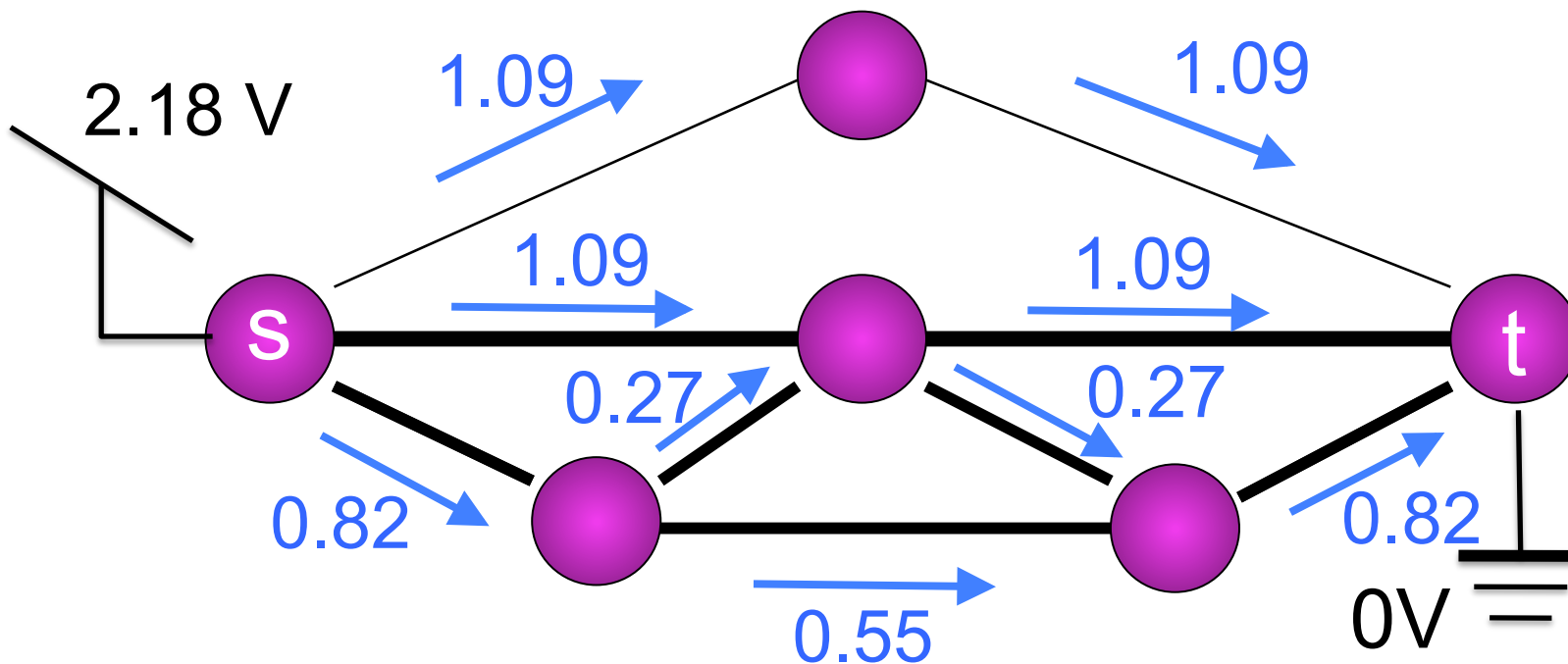
1. Try the electrical flow.



Maximum flow problem, electrical approach

[Christiano-Kelner-Madry-S-Teng '11]

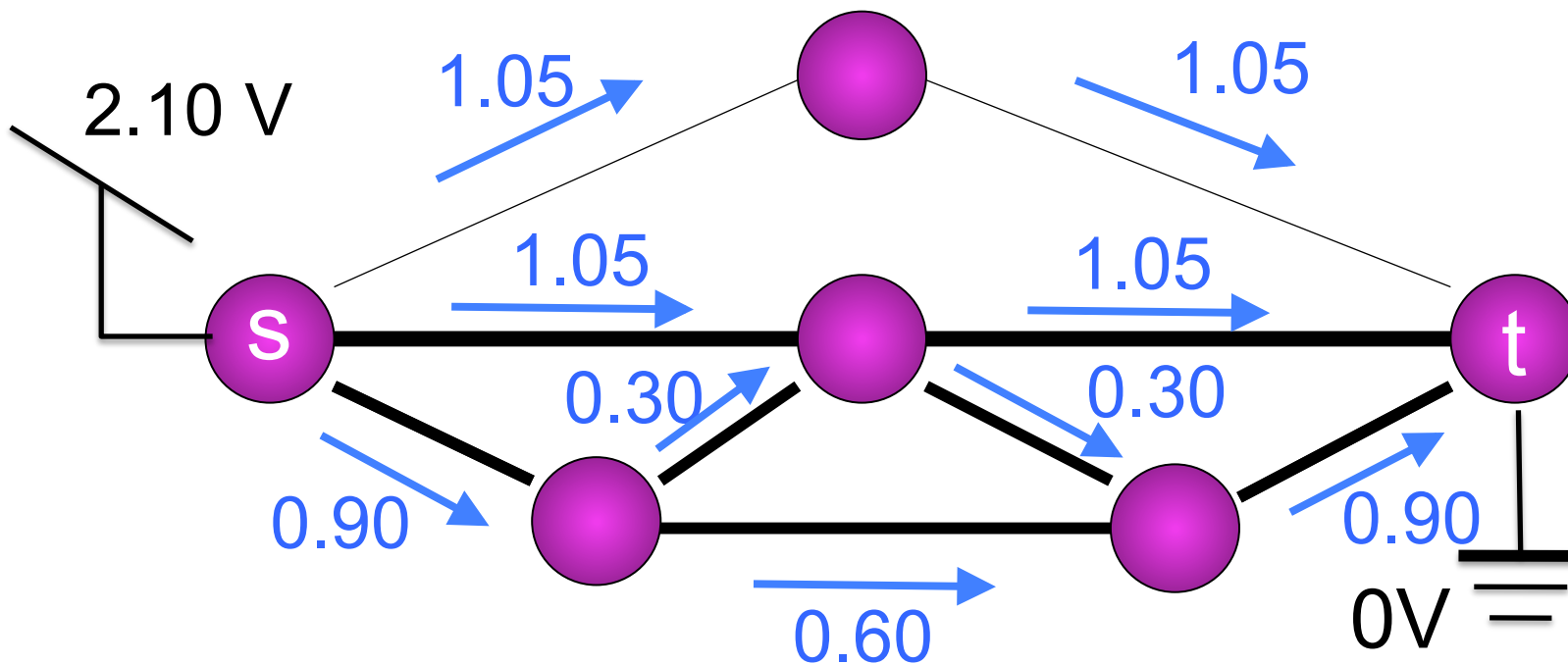
1. Try the electrical flow.
2. Increase resistance when too much flow



Maximum flow problem, electrical approach

[Christiano-Kelner-Madry-S-Teng '11]

1. Try the electrical flow.
2. Increase resistance when too much flow



Solving linear equations in Laplacians

For energy minimization and
computation of eigenvectors and eigenvalues

Can do it in time nearly-linear in the
number of edges in the graph!

Key ideas:

how to approximate a graph by a tree
or by a very sparse graph

random matrix theory

numerical linear algebra

Approximating Graphs

A graph H is an ϵ -approximation of G if

for all x

$$\frac{1}{1 + \epsilon} \leq \frac{x^T L_H x}{x^T L_G x} \leq 1 + \epsilon$$

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To solve linear equations quickly,
approximate G by a simpler graph H

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A very strong notion of approximation

Preserves all electrical and spectral properties

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Theorem [Batson-S-Srivastava '09]

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A powerful technique in linear algebra
many applications

To learn more

Lectures 2 and 3:

More precision

More notation

Similar sophistication

To learn more

See my lecture notes from
“Spectral Graph Theory”
and
“Graphs and Networks”