

Last lecture we considered the program

$$\max \alpha \quad (P1)$$

$$\text{s.t. } \alpha c \in \text{CH}(a_1, \dots, a_m)$$

and we assumed  $0 \in \text{CH}(a_1, \dots, a_m)$

We considered the dual program

$$\max c^T \gamma \quad (D1)$$

$$\text{s.t. } a_i^T \gamma \leq 1, \quad \forall i$$

And proved that for optimal  $\alpha_*$  and  $\gamma_*$ ,

$$\alpha_* = 1/c^T \gamma_*$$

We will now generalize these.

First,  $\alpha c \in \text{CH}(a_1, \dots, a_m)$  iff  $\exists t \geq 0, 1^T t = 1$  s.t.

$$\alpha c = A t, \quad \text{where } A = \begin{pmatrix} a_1 \\ \vdots \\ a_m \end{pmatrix}$$

If we set  $x(i) = t(i)/\alpha$ ,  $1^T x = 1/\alpha$  so  
larger  $\alpha$  corresponds to smaller  $1^T x$ , and it is  
equivalent to solve

$$\min 1^T x \quad (P2)$$

$$\text{s.t. } Ax = c, \quad x \geq 0$$

For the optimal  $x_*$ , we now have

$$C^T y_* = 1^T x_*$$

So, solutions to P2 upper bound solutions to D1.

But, what if  $0 \notin \text{CH}(a_1, \dots, a_m)$ ?

Or, what if there is no  $x$  s.t.  $Ax = c, x \geq 0$ .

Farkas' lemma

says that  $\exists \gamma$  s.t.  $a_i^T \gamma \leq 0 \forall i$   
and  $c^T \gamma > 0$

That is, value of D1 =  $\infty$ , by considering  $\mu \gamma, \mu \rightarrow \infty$ .

Warm up: consider the problem  $Ax = c$ , no assumptions on  $A$ .

either there is a solution, or

there exists  $\gamma$  s.t.  $\gamma^T A = 0, \gamma^T c = 1$

This is strengthened by

Farkas' lemma Exactly one of the following holds

i.  $\exists x \geq 0$  s.t.  $Ax = c$

ii.  $\exists \gamma$  s.t.  $A^T \gamma \geq 0, c^T \gamma < 0$

Proof If  $\exists \gamma$  s.t.  $A^T \gamma \geq 0$ ,  $c^T \gamma < 0$

then is no solution to  $i$  because

$$Ax = c \Rightarrow x^T A^T \gamma = c^T \gamma < 0$$

But,  $x \geq 0$  and  $A^T \gamma \geq 0 \Rightarrow x^T A^T \gamma \geq 0$ ,  
a contradiction.

To go the other way, note that

$\{Ax: x \geq 0\}$  is a convex set.

So, if  $c \notin \{Ax: x \geq 0\}$ , there is a

separating hyperplane:  $\gamma$  s.t.

$$\gamma^T c < \gamma^T Ax \text{ for all } x \geq 0.$$

As  $x = 0$  is possible,  $\gamma^T c < 0$

To see  $\gamma^T Ax \geq 0 \forall x$ , note that if  $\gamma^T Ax < 0$ ,

then  $\gamma^T A(\lambda x) \rightarrow -\infty$  as  $\lambda \rightarrow \infty$

So,  $\gamma^T Ax \geq 0 \forall x$

Conclusion: P2 is feasible iff D1 is bounded.

D1 is always feasible:  $\gamma = \bar{0}$ .

There are other variants like

Exactly one of these holds:

i.  $\exists \gamma$  s.t.  $A \gamma \leq b$

ii.  $\exists x$  s.t.  $A^T x = 0$ ,  $x^T b = -1$ ,  $x \geq 0$

The general standard LPs replace 1 with an arbitrary  $b$ , and are

$$\begin{aligned} P3: \quad & \min b^T x \\ & \text{st. } Ax = c, \quad x \geq 0 \end{aligned}$$

$$\begin{aligned} D3: \quad & \max c^T y \\ & \text{st. } A^T y \leq b \end{aligned}$$

We will see that these are dual to each other.

Weak duality is  $c^T y \leq b^T x$

proof:  $c^T y = y^T c = y^T A x \leq b^T x$ , because  $x \geq 0$ .

The complications are that there might not be  $x$  or  $y$  satisfying the conditions of P3 or D3, and the values of P3 and D3 can be  $-\infty$  or  $\infty$ .

To see why, consider the geometry

Geometric view of D3:  $A^T \gamma \leq b$  is  $\cap$  halfspaces  
 $\max c^T \gamma$  says to go as far as possible in one direction.

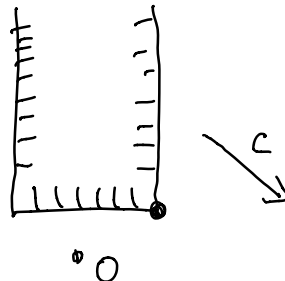
Example  $\gamma_2 \geq 1, \gamma_1 \leq 1, -\gamma_1 \leq 1$

if  $c^T \gamma = \gamma_1 - \gamma_2$   $c = (1, -1)$

$\gamma^* = (1, 1)$

if  $c^T \gamma = \gamma_2 - \gamma_1$

is unbounded: consider  $(0, \gamma_2)$   $\gamma_2 \rightarrow \infty$



$Ax = c, x \geq 0$  also looks like this.

P3 is feasible if  $\exists x$  st.  $Ax = c, x \geq 0$

D3 is feasible if  $\exists \gamma$  st.  $A^T \gamma \leq b$ .

They are infeasible when  $x$  or  $\gamma$  do not exist.

Weak duality tells us that

value (P3) =  $-\infty \Rightarrow$  D3 is infeasible, and

value (D3) =  $+\infty \Rightarrow$  P3 is infeasible.

Strong Duality Theorem:

P3 feasible & bounded  $\Leftrightarrow$  D3 feasible & bounded,  
 in which case have same value

We prove most of thrs.

First, it holds if  $b > 0$ .

proof. Recall  $A = (a_1 \dots a_m)$ .

Set  $\hat{x}(i) = x(i)b(i)$ , so  $b^T x = \mathbf{1}^T \hat{x}$

and set  $\hat{a}_i = \frac{1}{b(i)} a_i$ , so  $\hat{A} \hat{x} = Ax$

So, P3 now has form P2.

And,  $\hat{A}^T \gamma = (\hat{a}_i^T \gamma)_i = \left( \frac{a_i^T \gamma}{b(i)} \right)_i \leq 1$  iff  $A^T \gamma \leq b$ ,  
because  $b > 0$

So, D3 now has form D1,

and we know that P2 and D1 satisfy strong duality.

Consider general  $b$ , and D3 strictly feasible.

That is  $\exists \gamma_0$  st.  $A^T \gamma_0 < b$ .

Set  $\hat{\gamma} = \gamma - \gamma_0$ .  $\hat{b} = b - A^T \gamma_0$ . So  $\hat{b} > 0$

And,  $A^T \hat{\gamma} \leq \hat{b} \Leftrightarrow A^T (\gamma - \gamma_0) \leq b - A^T \gamma_0 \Leftrightarrow A^T \gamma \leq b$ .

$$c^T \hat{\gamma} = c^T (\gamma - \gamma_0) = c^T \gamma - c^T \gamma_0.$$

$$\text{And, } \hat{b}^T x = b^T x - \gamma_0^T A x = b^T x - \gamma_0^T c = b^T x - c^T \gamma_0$$

$$\text{So, } c^T \gamma = b^T x \Leftrightarrow c^T \hat{\gamma} = \hat{b}^T x$$

and the solutions are the same.

What if  $\exists y_0: A^T y_0 \leq b$  but does not exist  $A^T y_0 < b$ ?

Then  $\exists i$  s.t.  $A^T y_0 \leq b \Rightarrow a_i^T y_0 = b(i)$ ,

so  $y_0$  is restricted to a subspace.

Will handle this in homework.

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How to tell if LP is feasible & find  $y$ :

To find  $y$  s.t.  $A^T y \leq b$ ,

solve the program  $\min t$  s.t.  $A^T y \leq b + t\mathbb{1}$

$\Leftrightarrow \min t$  s.t.  $A^T y + t\mathbb{1} \leq b$

We know is feasible for big  $t$  and  $y=1$ .

If can achieve  $t \leq 0$ , is feasible

Can rewrite by choosing  $t_0$  s.t.  $b + t_0\mathbb{1} \geq 0$ ,

And solving  $\min t$  s.t.  $A^T y + t\mathbb{1} \leq b + t_0\mathbb{1}$

The rhs,  $b + t_0\mathbb{1}$  is now positive.

Is called a Phase I problem.

Then solve the original LP in Phase II.

Note: solving problems like  $\max c^T y$  s.t.  $A^T y \leq b$

is essentially equivalent to testing feasibility

First, ask if  $\exists y$  s.t.  $A^T y \leq b$ .

If so, ask if  $\exists y$  s.t.  $A^T y \leq b$  and  $c^T y \geq 0$  ( $(c^T y = 0)$ )

now, play 20 questions...

if yes try  $c^T y \geq 1$ ,  $c^T y \geq 2$ ,  $c^T y \geq 4$ ,  
doubling until get a "no".

Then do binary search.

Both infeasible?  $Ax = c$ ,  $x \geq 0$   $A^T y \leq b$

consider  $A = \bar{0}$   $c = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$   $b = \begin{pmatrix} -1 \\ -1 \end{pmatrix}$



## Complementary Slackness.

$$P: \min b^T x \\ \text{st. } Ax = c, x \geq 0$$

$$D: \max c^T \gamma \\ \text{st. } A^T \gamma \leq b$$

Put slack variables  $s$  into  $D$ :

$$\max c^T \gamma \quad \text{st. } A^T \gamma + s = b, s \geq 0$$

$$\begin{aligned} \text{The duality gap is } b^T x - c^T \gamma &= b^T x - x^T A^T \gamma \\ &= x^T (b - A^T \gamma) = x^T s \end{aligned}$$

$$\text{So, } P=D \Rightarrow x^T s = 0.$$

## Complementary Slackness Theorem

These are equivalent:

- i.  $x_*$ ,  $\gamma_*$  and  $s_*$  are optimal
- ii.  $x_*^T s_* = 0$
- iii.  $x_*(j) s_*(j) = 0$  for all  $j$
- iv.  $s_*(j) > 0 \Rightarrow x_*(j) = 0$

i  $\Leftrightarrow$  ii by duality gap arg.

ii  $\Leftrightarrow$  iii by  $x_* \geq 0, s_* \geq 0$

iii  $\Leftrightarrow$  iv by logic,  $x, s \geq 0$